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**System for Environmental and Agricultural Modelling;
Linking European Science and Society**

Modelling Framework (SeamFrame) requirements

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SEAMLESS integrated project aims at developing an integrated framework that allows ex-ante assessment of agricultural and environmental policies and technological innovations. The framework will have multi-scale capabilities ranging from field and farm to the EU25 and globe; it will be generic, modular and open and using state-of-the art software. The project is carried out by a consortium of 30 partners, led by Wageningen University (NL).

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General information

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Input from (Task and Activity codes): T1.2, Activity 1.2.1
Output to (Task and Activity codes): T5.2, Activity 5.2.3
Related milestones: M 5.2.2

Executive summary

In modern software engineering, *software frameworks* are fundamental to software development. A software framework provides a set of reusable libraries and classes to build applications. Examples are the Smalltalk model view controller (Deutsch, 1989), or the MacApp, the "Macintosh Application Framework" (<http://developer.apple.com/tools/macapp/>). More recently, the Java software framework (J2SE and J2EE) and the Microsoft .Net framework are providing easy and widespread access to software frameworks to an unprecedented number of developers.

A *modelling framework* is analogous to a software framework, with the specialisation in providing reusable components for building mathematical models. There are many modelling frameworks on the market, examples are MATLAB, Modelica, and so on (the list cannot be exhaustive, see <http://www.idsia.ch/~andrea/simtools.html> for a broader view).

An *integrated modelling framework* is an extension of a modelling framework, which supports multiple modelling domains and paradigms. The number of integrated modelling frameworks is considerably more limited, especially if we restrain to the intersection of social, economic and environmental modelling. We list some of the most notable initiatives in the various fields.

Economic modelling frameworks. GAMS (general algebraic modelling system, <http://www.gams.com>) and GTAP (global trade analysis program, <http://www.gtap.agecon.purdue.edu>) are some of the most used modelling systems in the agro-economic domain. They can also account for social variables, such as unemployment.

Environmental modelling frameworks. If we limit to the agricultural domain, the list is quite limited. There is no 'real' framework according to the definition, but APSIM, STICS and CropSyst provide some of the functionalities. When we consider the water management sector, we find many examples, such as TIME (the invisible modelling environment), IMT, OpenMI, and OMS.

Other **modelling software environments** of notable interest are SME, MMS, ICMS, Tarsier, Modcom, Simile, but they are integrated modelling environments, not frameworks. This means that they can be used to perform assessments, analyses, decision support, but they do not provide programming structures such as classes, components, objects, design patterns to be used to create end-user applications.

In this document we will express the requirements imposed by the SEAMLESS project vision on the SEAMFRAME modelling framework and we will critically assess these requirements against a suitable set of existing modelling frameworks. As a result, we shall be able to understand what to pick up and what to drop from these previous experiences in order to improve the trade-off between re-use and innovation, and maximise our users' satisfaction.

1 Introduction

1.1 Inspiration

The SEAMLESS project has the overall ambition of providing a *methodological* framework (SEAMLESS-IF) to support the ex-ante analysis of European agricultural management policies at all scales, from market level down to biophysical systems level. The SEAMLESS-IF will enable:

1. Analysis at the full range of scales, whilst focusing on the most important issues emerging at each scale;
2. Analysis of the environmental, economic and social contributions of a multifunctional agriculture towards sustainable rural development and rural viability;
3. Analysis of a broad range of issues and agents of change, such as climate change, environmental policies, rural development options, effects of an enlarging EU, international competition and effects on developing countries.

And this will be made possible thanks to an integrated and operational framework, named SEAMFRAME, with the following specific objectives:

1. To develop and test a multi-perspective set of economic, social and environmental indicators of the sustainability and multifunctionality of systems, policies and innovations in agriculture and agroforestry, and to establish, as far as possible, threshold values for these indicators and/or to enable trade-off analysis.
2. To provide quantitative and qualitative tools and databases for integrated evaluation of agricultural systems at multiple scales and for varying time horizons.
3. To develop a software architecture that allows reusability of model and database components and knowledge, also ensuring transparency of models and procedures developed.

1.2 Key ideas

SEAMFRAME will be based on the following key ideas:

First, the language used to represent models within SEAMFRAME will be declarative and not imperative. This means that a model will be represented as a set of facts and relations that are true about the model, rather than as an implementation in a specific compilable or compiled language. Declarative representation makes models far easier to re-use and combine, and much more transparent than implementations within a traditional, code-based, model structure. Thanks to the declarative modelling approach, the model can be saved in a standard, XML-based model-representation language. A declaratively-represented model can then be used to produce (for example): a description of the model (e.g. HTML); an executable version of the model; a transformation of the model (e.g. to simplify it, thus addressing the scaling problem).

Second, SEAMFRAME will use ontologies (structured specification) of data, models and tools, facilitating their retrieval from digital repositories and integration into workflows (a workflow is a particular arrangement of data, models and tools). Modellers will thus gain transparent access to each other's work (Note: SEAMFRAME will provide facilities to use the many models that are currently in use, thus preserving past investments and extending an invitation to researchers who are not part of SEAMLESS per se).

Third, SEAMFRAME will provide a mechanism to store comments, conversations and citations about models, data and workflows. An intelligent search agent will enable any user to retrieve and combine information from 1) model specifications, 2) model, data, or workflow metadata and their place in an ontology, 3) comments, conversations and citations. Thus, a researcher faced with the task of modelling a certain system can find not only all suitable models, but also the assumptions underlying those models, experiences of other researchers in using those models, and the outcomes of other studies in which those models were used. A decision maker faced with an analysis in which modelling was used, can use SEAMFRAME to find other studies in which the same models were used, other models that could have been used, and conversations about the history and suitability of the models that were used.

2 Environmental modelling frameworks requirements

Do we need another Modelling Framework? After all, we have a good number of Modelling Frameworks, purposely designed to solve the modelling problems one can encounter in many fields, from economics, to engineering, through natural sciences. Yet, we want another modelling framework, because it looks like we are not satisfied with the current ones.

Software frameworks provide programming constructs and artifacts (e.g. classes and components) that can be re-used to build software applications. Among others, .NET and J2EE are two examples of software frameworks, since they provide a set of libraries and classes with which the programmer can write new applications. Moreover, they provide tools, such as compilers and some of these tools have a graphical interface, such as an Integrated Development Environment.

In the same way, a modelling framework is a set of software components which can be used to assemble a software application for designing and experimenting with models. The libraries and classes are targeted to develop models, which can be packaged into applications. Tools, such as simulators or optimisers, operated on models, and a visual modelling environment can be useful to interactively develop a model or to set up a modelling scenario.

2.1 Problems of current modelling tools

Before listing the requirements of what we expect to be a good modelling framework, let's briefly summarise the problems we have encountered with the current ones:

1. models *are* applications. There is nothing inherently bad in this, but the problem is that bundling data, algorithms and the graphical user interface of a model in an application makes the model very hard to re-use out of its original context. Most models are therefore monoliths.
2. Models are nearly impossible to maintain, they can hardly evolve. Once a model, design and implemented as a monolithic software entity has been deployed, its evolution is totally in the hands of the original developers. While this is a good thing for intellectual property rights and in a commercial environment, this is absolutely a bad thing for science and the way it is supposed to progress. Independent revisions and third-party contributions are nearly impossible.
3. Models can not be independently tested. This issue is related to #2, since models often do not come with associated data sets for testing. Moreover, the adoption of object-oriented programming, while it is a good thing for model reusability and portability, it makes things more complex for testing, because of a number of problems such as observability in virtual method calls and state dependent behaviour of objects (Pezzè and Young, 2004).
4. Models are difficult to reuse. This problem is also related to issue #1, since monolithic models display a strong level of internal cohesion, and, if a modeller is interested in reusing a particular function within a bigger model, she can find it very hard to isolate and extract it, given the strong dependencies existing in the source code.
5. Inefficient use of resources. This issue is closely related to the preceding one; given that models are difficult to reuse, modellers and programmers are re-implementing the same things over and over, both in terms of models and tools used to operate on the models.
6. Models are not transparent

7. Models are platform specific

2.2 Tackling the problems

How can we solve the six (but there may be many more) issues we listed above? Many groups are working hard at it, but some of them are hard nuts to crack and it is unavoidable that, for the present time, there will be an overlap of efforts. This can be seen as a waste of resources, but it can also be seen as an evolutionary design effort, where the best ideas and practices (or the most popular) will emerge to provide a common and shared basis for environmental modelling. Moreover, the wide variety of models we encounter in environmental modelling, let alone other modelling domains, will provide food for thought for many researchers in the coming years.

As in any software problem there's no 'silver bullet' (Brooks, 1987). Yet, we have identified a set of approaches and methodologies which have been successfully adopted and used so far in diverse modelling framework efforts:

1. Knowledge management. Knowledge is a vague word, it means everything and nothing. In this context 'knowledge management' means to organise knowledge on models and data by means of structuring information. Semantic networks, one of the first attempt to represent knowledge, are an example (see Durkin, 1994 for a general book on Expert Systems and Knowledge Representation). Moreover, the Semantic Web initiative (<http://www.w3.org/2001/sw/>) is proposing shared web ontologies, as an evolution of semantic networks that can be used to univocally denote modelling concepts.
2. Object-oriented software development. O-O programming is nothing new, but it has proven to be a successful key to the design and implementation of modelling frameworks. Models and data can be seen as objects and therefore they can exploit properties such as polymorphism, data abstraction and inheritance.
3. Design patterns. The adoption of design patterns in programming (Gamma et al., 1995) has been proven to be a major factor for reuse, if not of code, at least of ideas and solutions. A library of design patterns for environmental modelling would be an interesting contribution. The modeller should create new models looking up at simple specifications in the form of patterns and code snippets.
4. Component-oriented software development (see Szyperski et al, 2002). Objects (models and data) should be packaged in components, exposing for re-use only their most important functions. Libraries of components can then be re-used and efficiently integrated across modelling frameworks. Yet, a certain degree of dependency of the model component from the framework can actually hinder reuse.
5. Support for testing. Models should be testable and they should be distributed together with their pre and post conditions and sets of data for testing. Techniques such as unit testing (<http://c2.com/cgi/wiki?UnitTest>) have been successfully adopted in model development.
6. Support for pre-conditions and post-conditions. It becomes important to adopt a 'design-by-contract' approach in modelling, borrowing this concept from software engineering. (Meyer, 1992). Each model will impose pre-conditions on the values of its inputs (e.g. admissible ranges) and post-conditions on the outputs, which can also be expressed as complex logical statements. The use of pre and post-conditions will make possible the use of the testing technique of 'unit tests' (Jorgensen and Erickson, 1994, Beck, 2003), enhancing the overall reliability of the system.

7. Support for documentation. Model equations should contain symbols which have their complete meaning in the ontology. The equations could be written in a declarative format (e.g. MathML and/or LaTeX) and then, each symbol could be associated with its meaning.

2.3 The benefits of the specifications

Why should ever a modeller take the trouble of following the complex specifications imposed by a modelling framework? The answer is easy: because he will get much more in return, by making a small investment in learning how to use the framework. Surely, the investment must be moderate and the return must be substantial, otherwise it will be better to continue as usual.

Here we list some of the expected returns, which become the requirements of a modelling framework. The framework shall provide:

- discrete units of software which are re-usable even outside the framework, both for model components and for tools components. Not an easy one to achieve since, as already pointed out, a certain degree of dependency, at least on data structures, is unavoidable;
- declarative modelling: among the multiple benefits, it allows for portability, reuse and openness of the knowledge embedded in models;
- software tools to facilitate model development, structuring and organising modelling 'knowledge';
- seamless and transparent access to data, which are made independent of the database layer.
- a number of tools (simulation, calibration, etc.) that the modeller will be free to use (including a visual modelling environment);
- a model repository to store your model and to share it with others.

3 SEAMLESS technical framework requirements

Collection of requirements has started during a meeting held in Wageningen on the 23/24 June 2003. The first set of requirements drove the description of the Technical Framework Working Package within the IP preproposal. Requirements are continuously being collected, being an integral part of the development process based on agile techniques (Beck, 2000).

3.1 Applications

Different applications define the main types of usage for the framework. Three types of user have been defined:

- Prime users: take or prepare decisions at a political level – primarily DGs (Agriculture and Environment) of the European Commission.
- Other end-users: national agencies, representative groups, OECD, etc. They may take or prepare decisions at national or regional level, or represent stakeholder groups.
- Model and application developers/modellers: use the SEAMFRAME components to build models and targeted applications.

These groups have been further detailed according to their roles:

- Coders: implement models, applications and tools.
- Linkers: link existing models and applications.
- Runners: execute existing models, but they create and define scenarios.
- Players: play simulations and experiments comparing scenarios and making analyses.
- Viewers: view the players' results, have a low level of interaction with the framework.
- Providers: provide inputs and data to all other user roles.

The following table displays a match between user types (rows) and user roles (columns)

	Coders	Linkers	Runners	Players	Viewers	Providers
Prime Users				√	√	
Other End-users ¹			√	√	√	√
Technical Users	√	√	√			

¹ End-users include all users who are neither modellers (technical users) nor policy makers (Prime Users) and they include national policy development agencies, farmers' representative groups, etc.

Use scenarios and requirements will be now elaborated for the user types.

3.2 SEAMLESS for the policy maker within DGs – Prime Users

This version of SEAMLESS is a key requirement of the IP call and it is addressed to the Prime Users; supporting policy making through use of social, economic and policy modelling components. Previously developed tools integrating biophysical and economic processes, agent based modelling, participatory decision making, multi criteria decision analysis, etc., will be used at different scales to design, synthesise, and analyse (evaluate) policy impacts at different scales (farm/regional/national/European) and on different sectors (industrial/social/environmental).

Use case 1 (Policymakers): A policymaker (not a modeller) requires a set of tools for evaluating impacts of the newly agreed restructure of the EU CAP from a multicriteria perspective. Several new, not formerly considered aspects will need to be included; rural development, demand for locally produced products, etc. The balance between local, regional and national level effects of policy decisions should be considered. The tools must combine state-of-the-art knowledge from different disciplines (e.g. a crop model with an economic model and a policy model) and yet be transparent and easy to use. The tools must be easy to modify and re-use even if their designers are not present.

This leads to the following requirements:

A focus on policy-relevant meta-data:	One of the novelties with the SEAMLESS approach is the combining of different types of models for policy evaluation purposes. This creates the need for new meta-data for all types of models included.
Application development environment is open-source	Code can be submitted to reviews from external groups. Add-ons and new features can be contributed by groups adopting the SEAMLESS software. Research investments are preserved, since no knowledge is lost: everything is public, accessible and, if needed, can be re-implemented, migrated to other approaches/platforms (see Eric S Raymond article “The Cathedral and the Bazaar” http://www.firstmonday.dk/issues/issue3_3/raymond/)

3.3 SEAMLESS for Other End-users

In this version of SEAMLESS the user will have more space to build their simulations with (e.g. regional-) specific scenarios, to explore and assess all point of view of various stakeholders.

Use case 2 (Farmers’ association): A farmers’ representative in a facilitated workshop wants to explore the idea of converting to organic (biological) status. How will this affect the profitability of the farms? What alternative cropping options should be considered? Need to simulate farms via FSSIM. Develop a program and implement models to simulate farm activities in order to provide support for planning, accounting for economic, technical, environmental, and labour perspectives. The farm is seen as a spatially explicit unit, in which different production (in the broad sense) activities may or may not take place: crops, orchards, livestock, forestry. Some of the models will be dynamic, others will be static. There will be an economic budgeting model. Management will account for machinery availability and characteristics, which extends the set of rules to fire events. Need to test FSSIM performance against experimental farm data. Need to evaluate scenarios (settings of resources, factors, and actions with specific or

stochastic weather and on specific soils). Need to validate scenarios before run. Need to save each scenario simulation outputs.

This use-case leads to the following requirements:

Easy to use	Specific applications with customised user interfaces will need to be developed for scenario exploration with particular groups of farmers.
Reliable	Farmers and others directly related to land use issues should be able to pick recommended or “ empirically proven” model combinations for sustainability estimations

3.4 SEAMLESS for the model and application developer – Technical Users

This is the version of SEAMLESS which is most sought-after by European scientists and which current SEAMLESS consortium members wish for; an environment for the coherent development of models and their simulation.

The meeting, being software oriented, further specified this application into

1. Development of conceptual models, a tool for modelling
2. Development of “components”. Components can be solvers, numerical integration algorithms, simulation engines or statistical analysis routines, as well as models.
3. Development of tools from these components, that are integrated across scales (temporal and spatial), and disciplines (social sciences, economics, natural sciences).

Use case 3 (Model developers): A research centre wants to use SEAMLESS as a development platform to produce models which are easy to integrate with the work of different research groups. The research group also wants to preserve the investment made in the model development, since language obsolescence often leads to periodical re-implementation of the models.

The requirements emerging from this use case are for an environment which:

- *makes it easy to integrate models*
- *makes it easy to assess and achieve interoperability*
- *provides methodology for preserving coding investment*
- *is self-documenting*
- *facilitates knowledge-based support to modelling*
- *facilitates a model repository*
- *facilitates web-based distribution*
- *facilitates version control*
- *facilitates use of multiple modelling paradigms*
- *facilitates spatial and temporal modelling at different scales*
- *facilitates quality control, through standardised representation, and through easy use of tools for model comparison and testing*

All these requirements inevitably lead to a solution, which becomes a requirement itself:

- **A declarative approach to modeling:**

This requires separating a model from the computational aspects which make possible the transformation of the model input into an output. The model contains the “rules” of the transformation, not the algorithm performing the transformation. For instance, in the case of a model based on sets of Ordinary Differential Equations the model consists of the equations, not of the numerical integration routine, the database access routines or the graphical visualisation or statistical processing of the outputs.

From Simile’s website:

In declarative modelling, we represent a model not as a series of assignment and control statements, but as a set of facts that are true about the model. The order in which we present the facts is (unlike a procedural program) irrelevant. The full set of facts defining a model actually constitute a specification for the model: given these facts, and knowledge about what the symbols mean, someone else can construct a working version of the models.

This implies:

- **The model must be specified using a declarative language.** The language provides a formalism to express the modelling facts. The language provides constructs to define the model interface and the model constructs.
- **The language must be semantically rich.** This requirement implies that the elements of the modelling language must have a meaning that can be understood by a computer. This implies that the language elements must be defined. The repository for these definitions, which are the knowledge about the model, are contained in what is called an ontology, i.e. a schema (or DTD) for the necessary meta-data. Thus a key task for SEAMLESS is to deliver this ontology. Recent research on the Semantic Web (<http://www.sematicweb.org>) shows how XML and Schemas can be used to represent ontologies. This will enable SEAMLESS to handle an (evolving) ontology, and shall aim at delivering a Schema (and a DTD for creation of XML bindings) for the validation of the necessary meta-data.

In XML (extensible markup language), as with HTML, information is stored together with tags which define what the information is. The difference is that HTML tags are pre-defined, whereas XML tags can be defined in a case-specific ontology. See for example the following piece of XML code; the language elements are tags such as <INFLOW>, <OUTFLOW> etc.:

```
<STOCK NAME = “BUDWORM” LOWER=0>  
<INIT>5</INIT>  
<INFLOW NAME=”BIRTHS”>  
    R*BUDWORM(1-BUDWORM/K)  
</INFLOW>  
<OUTFLOW NAME=”DEATHS”>  
    (BUDWORM**2)/(1+BUDWORM**2)  
</OUTFLOW>  
</STOCK>
```

(From Villa’s paper “Integrating Modelling Architecture: a declarative framework for multi-paradigm, multi-scale ecological modelling”, Ecological Modelling 137 (2001) 23-42).

The requirement that modelling must be declarative, and achieved by a semantically rich modelling language, implicitly satisfies a number of other requirements:

<p>Models are self-documented</p>	<p>This is to a certain degree inherent to the DM methodology, since the way the model is written makes clear what is an input, what an output, what a state and what a parameter. DM also makes it easy to develop multiple tools for model analysis and description, for different users / purposes.</p> <p>The model of the stock component named “budworm” is clearly self-documenting (even if the declaration of the initial value equal to 5 in the model specification is objectionable).</p> <p>Another example of self-documentation (beyond other things) is provided by ECOBAS (http://www.wiz.uni-kassel.de/ecobas.html) where models expressed by a declarative approach can be searched, downloaded, compiled, and run.</p>
<p>Knowledge based support to modelling</p>	<p>This requirement was not expressed in the previous use case, but it was set as a priority by the group. Knowledge-based support comes “for free” once we provide <i>semantic meta-data on model teleology</i>. Teleology is the model purpose and it can be formally expressed via model meta-data (facts associated with the model) and inferred from the input to output transformation.</p>
<p>A model repository</p>	<p>Models can be stored in a repository and accessed for later usage, queried, compared, evaluated.</p>
<p>The model repository must be under version control</p>	<p>It should be possible to track changes to the model equations made by different authors and to view a ‘history’ of the development of a model.</p>
<p>Model “quality” must be verifiable where possible</p>	<p>Here, the word “quality” should be defined according to the actual use. Are we talking about programming structure (e.g. a “good” model is one written clearly)? Are we talking about validated outputs? About how easy it is to use? It must be remarked that many economic and policy models are also hard to validate and / or verify.</p> <p>For models of natural systems, this requirement can be satisfied with benchmarking tools that should be provided. Such tools will provide standard statistical tests to assess model quality against data.</p> <p>Policy models are harder to benchmark, but some efforts have been done in the field of Participatory Decision Making, using agent based models, trying to reach a consensus based on empirical observations of the agent behaviour.</p> <p><i>Note: In any case, this requirement is a sensible one and it needs to be discussed together with economists and social scientists.</i></p>
<p>Web-based distribution of models</p>	<p>For an example, see the ECOBAS web site (http://dino.wiz.uni-kassel.de/ecobas.html). Models can be sought after on a website according to their metadata and finally they can be downloaded, either in binary or source code format.</p>
<p>Web based deployment of models</p>	<p>Models and tools can be packaged together to provide a ‘service’, that is a transformation of data over the internet.</p>

Multiple modelling paradigms	(static/dynamic/stochastic/deterministic/explanatory/qualitative/conceptual). A Lattice of model classes should be listed. (Note: this is also meta-data, which can be covered within the Schema)
Spatial and temporal modelling at different scales	Models shall be available at different scales, over time and space. For instance, there will be models with characteristic times ranging from hours to months. In the same way, some models will be valid only over a limited area of a few hectares or on a much wider region (e.g. NUTS2-3).

Use case 4 (Application developers): The research institute has access to their collection of SEAMLESS models, including models developed by other partners. They want to develop stand-alone applications for different kind of users: for end users, to use models to evaluate the impact of regional policies or technological innovations; for policy makers, to evaluate the impact of new laws and regulations.

The requirements associated with this use case are²:

An environment for the development of workflow management	Must support a workflow development environment to create the application as a sequence of model transformations by tools, data manipulations and processing. This ensures that SEAMLESS allows the development of packaged customised applications. (see http://www.wfmc.org/)
Repositories for data, models, and tools	While the justification for the repository for models has been given in the previous use case, and we cannot even think of not having data repository (the question is how to implement it), <i>tool repositories</i> are a novelty. Tools must have the same status as models. Tools are the implementation of algorithms, they could be numerical integration routines, or a linear program solver, implementing the simplex algorithm. We need metadata for tools, to describe what they do, and how they are interfaced with models.
Allows web based deployment of tools	A tool providing a service (e.g. integration of a model) can be offered as a web service. The Semantic Web initiative is all about this. Links to the GRID computing initiative. Thanks to semantically rich interfaces, models become searchable in the webspace and an “agent” can manage a complex simulation coordinating the different models taking part in it. Possible links to the concept of “model federations” (see the DMSO HLA, High Level Architecture https://www.dmsomil/public/transition/hla)
Must support software quality checking	The quality of the software components must be testable, by using unit tests, integration test and regression tests.

3.5 Other potential use scenarios for SEAMLESS for application and model development

1. A three-year project needs to build a crop rotation model by coupling 4 existing models - a crop model and a natural vegetation model both in Fortran, a water balance model in

² This use case needs to be expanded to include those elements from the other use cases set out below which illustrate new requirements not already covered

Pascal, and a soil organic matter model developed in a graphical modelling environment with code export possibility to C++. The partners need to calibrate and validate their models using data from two years of field experiments (executed in the course of the project), stored in a common database. The project has meteorological data which are incomplete. Both the experimental data and the meteorological data will be checked and revised in the course of the project. Furthermore one project member doesn't trust the quality of the crop model, and needs to do some extensive testing, and perhaps further model development.

2. Build an application that lets users pick component models from a repository (the repository holds 10 crop models, 10 soil models, 10 aphid models, 10 meteo models, ..) and connect them to form ecosystem models.
3. Develop a cropping systems simulator (CSS) from components to simulate soil structure, soil water, soil C-N, annual and perennial crops, orchards, forestry, pesticides, diseases, weeds. Different participants independently develop different model components, according to their specific expertise. The simulator should allow the use of alternatives for model components e.g. developed by independent groups, and new types of component (e.g. an insects component). Need to handle state and time driven events. The CSS must work as a stand alone application, or driven (e.g. in many instances) by a higher level simulator (e.g. a Farm Activities Simulator). CSS performance will be tested against experimental field data, and scenarios will be evaluated (settings of resources, factors, and actions with specific or stochastic weather and on specific soils). Scenarios need to be validated before each run, and outputs from each run saved.
4. A Chinese professor collaborates with a SEAMLESS project, uses SEAMLESS to develop models, and develops a course in modeling at his university based on these models. No money to pay for a SEAMLESS license
5. (Current FP5 project) In a greenhouse climate control project one partner is developing an hydrological model using software under Linux. Another partner provides a crop growth model to allow climate control optimization based on crop performance, developed using FORTRAN in Windows. Does SEAMLESS offer a solution?
6. (Current FP5 project) Selection of structurally detailed statistically testable ecological models Objectives: This project will investigate the costs and benefits of models that provide a detailed description of ecological processes, using tools and example data sets available. The approach will be to select models, which are empirically justifiable in that they contain an amount of detail in their structure, which is appropriate to the data which are available. This appropriateness will be evaluated using formal statistical tests. By doing this it is intended to go as far as the information allows, but strictly no further.

3.6 Some more requirement issues

1. Portability (Linux/Windows). It has to be remarked that legacy models cannot usually be ported if they are provided in compiled form. They can be only invoked as "web services" from an application, but they must reside on their original environment.
2. Legacy models: one strong requirement was that SEAMLESS should support both open and closed source submodels and tools, to allow for use of legacy and proprietary models. Open source models are models where the source code is freely accessible and re-distributable. Closed source models are those where the source code is either protected by an IPR agreement (even if the source code is accessible) or those where only binary code is available. Closed source components will inevitably be less portable.
3. Reusability of models/tools/data. Reusability is automatically achieved if we provide full access to the declarative modeling language we use to define our models.. It is the same methodology for preserving coding investment, covered above.

4. Interoperability. Maybe we also need a "Facility for Interoperability Testing" (FIT) aiding modellers/developers in delivering interoperable models, tools and services which can be used together. This may be covered by adequate meta-data. Checking the model and tools interfaces we can see whether models/tools/policies are interoperable.
5. The ability of using remote sensing data to calibrate and validate spatial models This is related to the "quality issue", but also to type of model. Within the meta-data set there must be information about this; whether it is an aggregated, point-base model, or a distributed. If we want to strictly address the issue of GIS models, there is a need for specific technical documentation. It may come in a later stage.

4 A comparison of existing modelling frameworks

During the meeting a list of 18 requirements emerged, which are listed and discussed in relation to the various suggested software solutions in Appendix 1. How should we prioritise these requirements?

Adopting the MoSCoW scheme (Must have, Should have, Could have, Would have) the requirements have been listed in descending order of number of votes received in the meeting. This voting highlighted the aspects thought to be important, but does not necessarily reflect the urgency with which the requirement should be or can be implemented.

	Requirement	MSCW	Priority
1	Uses declarative approach (formal representation of equations) for language independent model description (XML)	M-C	8
2	Knowledge-based support for modelling (e.g. advises users where coupling is appropriate)	M	8
3	Framework software is open source (e.g. GPL)	M	4
4	Allows for quantitative (static, dynamic, stochastic, deterministic, descriptive, explanatory...), qualitative and conceptual components	M	4
5	Supports both open and closed source submodels and tools	M	3
6	Version control for framework, components and scenarios	M	3
7	Facilitates self-documentation	M	2
8	Supports model and software quality checking	M	2
9	Allows web-based deployment of models and tools	C	2
10	Supports a variety of different users	M	2
11	Provides repositories for: a) data / models; b) solvers; c) knowledge	M	1
12	Provides a benchmarking environment	M	1
13	Portable between Linux and Windows	M	1
14	Allows development of packaged, customised applications	M	1
15	Reusable outside the framework	M	
16	Can handle an evolving ontology (tag definitions)	M	
17	Allows web-based publication of models and tools	M	
18	Allows specialised interactions between components (e.g. by using a workflow environment)	M	

On the basis of the above list of requirements, we selected four modelling frameworks (TIME, Modcom, IMA, OpenMI) and, with the help of the framework developers and supplemental material such as journal and conference papers, we checked how each one of the framework addressed the requirements.

This screening phase will be useful in extracting relevant design ideas and possibilities of software reuse in the design phase of SEAMFRAME.

4.1 TIME – The Invisible Modelling Environment

The Invisible Modelling Environment (TIME) is a new environmental modelling framework being developed within the Catchment Modelling Toolkit project in the CRC for Catchment Hydrology. TIME differs from existing modelling frameworks in a number of ways, particularly in its use of metadata to describe and manage models as well as the flexibility given to model developers to ‘pick and choose’ the components of TIME relevant for a given project. Functionality that is embedded as part of a monolithic core in other frameworks is included in applications under TIME on an as-needed basis using optional, interchangeable components. This flexibility extends to components that manage data and models, recognising that one approach does not necessarily fit all applications. TIME includes a number of small framelets supporting extension in key areas such as data representation and visualisation. All fundamental data types, such as rasters and time series, are defined within the data framelet, which supports the definition of new, compatible data types. The visualisation framelet allows the definition of ‘layers’, each providing a visual representation of some type of data, such as rasters or polygons. Multiple layers can be placed on a single ‘view’, such as overlaying a polygonal map on a raster. Views can be surrounded by ‘decorators’ such as axis and titles, each of which can be combined independently. TIME includes a number of tools, which operate generically on models, including an automatic user interface generator and various model optimisation tools. TIME is developed on the Microsoft .NET platform and supports the development of models in a variety of languages, including Visual Basic.NET, Fortran 95.NET, C# and Visual J#. TIME is currently being used to develop a range of modelling applications, including a library of rainfall runoff models and a model supporting assessment of stream ecosystem health under various flow scenarios.

4.1.1 Requirements matching

1. Uses declarative approach (formal representation of equations) for language independent model description (XML)

No. The model description (such as input and output definition, variable naming), is handled through formal metadata specification. Given that TIME is implemented in .NET it supports multi-language development, but it is up to the modeller to adopt a programming style as close as possible to declarative modelling.

2. Knowledge-based support for modelling (e.g. advises users where coupling is appropriate)

Not implemented, but the integral use of model metadata within the TIME environment supports the analysis of proposed model links through matching of data types. The lightweight architecture of the TIME core/kernel has the potential to support any knowledge-based model support system that can be expressed in model metadata.

3. Framework software is open source (e.g. GPL)

The CRCCH (Co-operative Research Centre on Catchment Hydrology) has a federal government requirement to assess the commercial potential of any CRC products. However, it is the intention of the CRCCH to distribute as much as possible of the system under an open source agreement.

4. Allows for quantitative (static, dynamic, stochastic, deterministic, descriptive, explanatory...), qualitative and conceptual components

Yes. The TIME architecture has been designed to flexibly support a range of modelling methods and approaches. In line with CRCCH needs, the current models developments are almost entirely quantitative.

5. Supports both open and closed source submodels and tools

Yes. Through multi-language support and the capabilities of the .NET system, TIME supports linking with compatible open and closed sources models and tools. In addition, a proposed development in cooperation with the European Open Modelling Interface (OpenMI) (www.harmonit.org) will increase the linking capabilities of TIME with a range of European hydraulic and hydrological models.

6. Version control for framework, components and scenarios

Framework and component development uses CVS for version control. No formal control of scenarios has been implemented.

7. Facilitates self-documentation

Yes. The metadata capabilities of both TIME and .NET support a reasonable level of self-documentation (assuming developers provide correct metadata and required fields when coding).

8. Supports model and software quality checking

No formal method for model and software quality checking has been constructed within the TIME environment.

9. Allows web-based deployment of models and tools

Yes. Models and tools will become progressively available from www.toolkit.net.au over the next three years.

10. Supports a variety of different users

Yes. Five major user types have been considered during the requirements analysis.

11. Provides repositories for: a) data / models; b) solvers; c) knowledge

a) yes. The toolkit website has been identified as the primary repository.

b) TIME supports pluggable solvers, but at present no specific solver repository is available within TIME. However, these would be handled similarly to a), above.

c) An information management system is under development, and a "toolkit assistant" that will act as the primary model knowledge system.

12. Provides a benchmarking environment

No. Benchmarking tools have been used for TIME development, but little development has been undertaken for model benchmarking.

13. Portable between Linux and Windows

.NET is currently Windows based. Open source development of the Linux equivalent (Mono www.go-mono.com) offers potential for Linux deployment.

14. Allows development of packaged, customised applications

Yes. The component-based approach used with TIME supports development of tailored user interfaces for collections of components linked together to form specific modelling solutions.

15. Models are reusable outside the framework

Generally, TIME components (packaged as DLLs) are not reusable, unless the whole of TIME core is provided.

16. Can handle an evolving ontology (tag definitions)

Not at present, but it will be possible through evolution of TIME metadata definition and utilisation.

17. Allows web-based publication of models and tools

Yes. See (9) above.

18. Allows specialised interactions between components (e.g. by using a workflow environment)

TIME supports the development of tailored components interactions through metadata manipulation.

4.1.2 Potential contribution to SEAMLESS

TIME is the result of many years of research and development by Australia's Co-operative Research Centre for Catchment Hydrology. Despite being focused on catchment modelling, the underlying ideas make it a source of inspiration for SEAMLESS. The fact of not being open-source hinders the reuse of the software code. Had it been possible, a number of data manipulation and visualization tools would have been available to SEAMLESS. The smart use of introspection (the ability to discover the software property within the program itself) will make it possible to develop SEAMLESS software components to be re-used in TIME and possibly vice-versa.

4.1.3 Contact details

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4.2 IMA: the Integrating Modelling Architecture

The IMA derives its power and generality from adopting the semantics of the natural entities represented (e.g. economic value, biomass, or nitrogen flow) as opposed to that of the execution workflow that calculates the desired results. The most general representation of a modeled entity in the IMA is a tree of interconnected modules, each corresponding to a precisely identified object of study. The declaration of each module can include an observation context that encompasses all aspects connected to scaling, such as granularity and extent in space and time, and can be manipulated by the investigator or by the system when mediating across different, compatible representations used together.

4.2.1 Requirements matching

1. Uses declarative approach (formal representation of equations) for language-independent model description (XML).

Yes. The IMA is a modular, extendible object system where both classes and objects are specified in XML. XML-specified modules can represent data, models, optimisers, algorithms.

2. Knowledge-based support for modelling (e.g. advises users where coupling is appropriate).

Yes. The IMA's primary goal is to give modellers the ability of using the bare conceptual bones of the problems while promoting a design discipline that automatically enforces constraints of semantics, space, time, and other applicable domains (e.g. consistency in measurement protocols or bibliographic source) - as well as the obvious constraints of storage type and units. Modules are tagged with semantic types (pointers into formally specified ontologies) and contain domain objects that represent cross-cutting aspects related to observation (space, time). Compatibility between all these is automatically enforced by specialised interfaces built over a common API. Domain types and ontologies can be added to the system in a plug-in fashion. The permanent storage functionalities and database interfaces have the ability of retrieving only semantics- and domain-compatible objects that will fit a precise role in an existing model structure. The domain functionalities are developed in the core engine and under implementation in the time and space domains. The semantic type functionalities are under development.

3. Framework software is open source (e.g. GPL).

Yes. Everything in the IMA is covered by the GPL, and there is no functionality that requires the use of closed-source software. This has been a main design goal for the IMA. All extensions use open source software (Mapserver/GEOS for GIS, R for statistics, PostgreSQL for permanent storage) although they can be implemented with commercial solutions if required.

4. Allows for quantitative (static, dynamic, stochastic, deterministic, descriptive, explanatory...) qualitative and conceptual components.

The IMA supports multiple modelling paradigms and is not by any means limited to equations as a way to describe a model. For modules whose specification requires equations (e.g. those whose state is calculated by integrating a differential equation), these can be specified entirely in XML if desired, although it is normally more intuitive to use some sort of expression of programming language. The IMA supports a full-fledged, object-oriented programming language and has plug-in support for other languages (Scheme, Javascript, Python, C/C++). Currently the modules implementing difference equation modelling, the STELLA importer (and probably the Simile importer

that will be developed) use CDATA sections and the internal IMA language compiler rather than MathML or other XML-based ways to express the equations. Supporting MathML if required would require very little effort.

5. Supports both open and closed source submodels and tools.

Yes. Everything in the IMA can be plugged in as an extension and all software with a C API can be used. One specialised class of objects handles interaction with closed executables, through proxy objects that range from command line drivers to CORBA/COM peers for enabled components. This allows legacy programs to be given the necessary semantic characterisations and wrapped at the executable level, becoming a component of a larger-scale model implemented in the IMA.

6. Version control for framework, components and scenarios.

Under development. The permanent storage interface allows version control and specialised, XML-specified “difference” objects are planned that can be applied to other objects to modify them. This is a central feature to enable a “bulletin-board” approach where the objects of discussion are actual data and models.

7. Facilitates self-documentation.

Yes. The core IMA engine has a template-based self-documentation system that uses templates to enable self-documentation of objects in formats such as HTML, text, or LaTeX. This system is currently used for all web-enabled database applications based on the IMA. Plug-in support for MIME types can be also plugged in on a class-specific basis. This feature is used to allow objects to intelligently select their proper multimedia representation given a MIME type (e.g. spatial objects will generate GIS maps, temporal objects will generate timeseries graphs, and spatio-temporal objects will generate animated maps, all as an answer to the same request for a image/png).

8. Supports model and software quality checking.

Under development. Storing accuracy information along with data and model is a crucial feature in an environment that allows arbitrary composition of data sources and processing algorithms (with associated compounding of error) and allows automatic rescaling of differently scaled information (with associated transformation error). Such features are not implemented in the IMA at this time.

9. Allows web-based deployment of models and tools.

Yes. This is a core requirement for all the projects that the IMA is currently employed in. A specialised IMA runtime runs as a multi-user server and a CGI IMA client allows full control of an IMA object database and hierarchy through the web. The self-documentation engine does the rest, allowing complete deployment of models, data, and analysis tools.

10. Supports a variety of different users.

Yes. IMA-enabled applications can be used as simple databases from the Web while modellers can use the IMA as an XML modelling tool and runtime environment. Different runtimes can be created very simply using policy-based design, supporting batch modelling, client/server interaction, or GUI interaction (currently not implemented).

11. Provides repositories for a) data/models; b) solvers; c) knowledge.

The IMA runtime has a virtual repository interface that uses XML-specified views and queries. It has been currently implemented on top of PostgreSQL out of consideration of stability, open source and availability of specialised spatial operator. All of the three

classes of objects mentioned in the requirement map into representational categories handled by the IMA and its permanent storage system.

12. Provides a benchmarking environment.

Not available. In general the explicit semantics of IMA modules allows many metrics to be calculated on them (e.g. the runtime system can estimate the resource requirements of a model by its representation, and enforce hard constraints on it before trying to allocate and run it).

13. Portable between Unix and Windows.

Yes. The IMA is written in ANSI C++ and has no dependence on particular OS architectures. All the development so far has been done on Linux.

14. Allows development of packaged, customized applications.

Under development. IMA models can be executed by a runtime and it's easy to package a model with its own runtime system. A feature in development is the translation of a whole model into C language for compilation and delivering as an executable.

15. Reusable outside the framework.

Yes. IMA modules are executed by a runtime that can assume many different forms and be hosted on a local computer or a server. Policy-based software design allows the runtime operation to be redefined in a very simple way.

16. Can handle an evolving ontology (tag definition).

Under development. IMA modules can be tagged with semantic types that point to specific ontologies. The issue of tracking evolving ontologies without losing semantic integrity is, anyway, extremely tricky. The SEEK project (<http://seek.ecoinformatics.org>) has a Semantic Mediation and a Knowledge Representation working group that is discussing how to deal efficiently with evolving semantics.

17. Allows web-based publication of models and tools.

Yes. the model repository can be easily accessed from the web.

18. Allows specialised interactions between components (e.g. by using a workflow environment).

Yes. The IMA is a workflow environment by its own nature, and it has close relationships to Kepler (<http://kepler.ecoinformatics.org/>) and Ptolemy II (<http://ptolemy.eecs.berkeley.edu/ptolemyII/>).

4.2.2 Potential contribution to SEAMLESS

IMA is a design, and parts of it have been implemented in IMT (Integrated Modelling Toolkit). IMA and IMT are highly relevant to SEAMLESS since many of the fundamental requirements are covered by IMA. A first assessment sees in the declarative modeling capabilities of IMA the most interesting features, together with the ability to combine tools and models in workflows. Finally, the knowledge base of SEAMLESS would benefit from being inspired by IMA.

4.2.3 Contact details

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4.3 Modcom

MODCOM's central concept is that of well-defined, self-describing component models, either written specifically for MODCOM or included through an adapter. A MODCOM simulation is constructed as a collection of interconnected components. MODCOM's component architecture provides a robust base for building flexible, domain-specific tools for such tasks as visual construction of components and simulations, specification of spatial relationships, and optimisation.

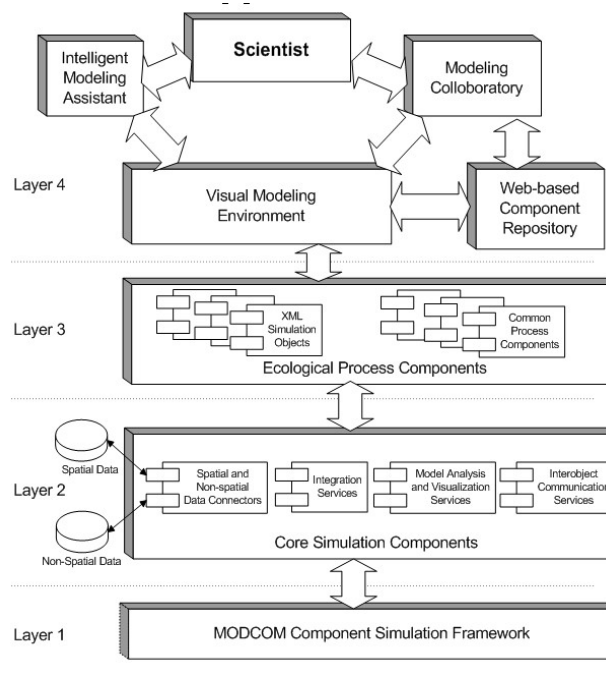


Figure 1. Proposed Simulation and Collaboration Architecture

The MODCOM core functionality has been implemented. A number of agro-ecological process components have been developed. Two tools for visual construction of simulation models have been recently developed.

4.3.1 Requirement matching

1. **Uses declarative approach (formal representation of equations) for language independent model description (XML)**

No. MODCOM components are defined at the binary level; such components can be written in a declarative language just as well as in Fortran, C/C++ or Java. It is anyway possible to automatically convert a Simile declarative model into a MODCOM component.

2. **Knowledge-based support for modelling (e.g. advises users where coupling is appropriate)**

Not available.

3. **Framework software is open source (e.g. GPL)**

Yes. The MODCOM source code is fully available.

4. **Allows for quantitative (static, dynamic, stochastic, deterministic, descriptive, explanatory...), qualitative and conceptual components**

MODCOM allows quantitative components. Extensions might be required for qualitative components.

5. Supports both open and closed source submodels and tools

MODCOM is written in C++ on the Microsoft COM platform and a .NET version is under development. The source code of a model, written in C# or in C++ can be made explicit, or packaged in a binary component.

6. Version control for framework, components and scenarios

The MODCOM framework is available under concurrent version control (CVS). Models can also be distributed under the versioning system, but there are no facilities for data and scenario handling.

7. Facilitates self-documentation

MODCOM components are defined at the binary level; MODCOM wants components to do their job but doesn't care how they do it. A component could make available the specification of the model it represents and documentation could be generated from that.

8. Supports model and software quality checking

A component could provide information about valid ranges for inputs; a checking component could be written to signal when those ranges are exceeded. A component could make available the specification of the model it represents; checks could be made on the basis of it.

9. Allows web-based deployment of models and tools

Currently no facilities, but MODCOM-based components and tools could be deployed through the Web.

10. Supports a variety of different users

Presently the model coder, who writes source code, and the model runner.

11. Provides repositories for: a) data / models; b) solvers; c) knowledge

Not currently. These tools are envisioned in a future release.

12. Provides a benchmarking environment

Not currently. Envisioned in a future release.

13. Portable between Linux and Windows

MODCOM is currently under porting to the .NET environment, for which a runtime environment is also available on Linux.

14. Allows development of packaged, customised applications

Yes. Assembling models and components allows to create specialised applications, targeted for a particular usage.

15. Reusable outside the framework

MODCOM models fully depend on the Modcom framework, in the same way as TIME models.

16. Can handle an evolving ontology (tag definitions)

Not currently supported.

17. Allows web-based publication of models and tools

Currently no facilities, but MODCOM-based components and tools could be deployed through the Web.

18. Allows specialised interactions between components (e.g. by using a workflow environment)

Yes, but it is up to the programmer to define the flow of the logic in the source code of an application which uses the MODCOM framework.

4.3.2 Potential contribution to SEAMLESS

MODCOM has many contact points with TIME. It can be considered a modeling and simulation framework and it has the advantage of having been thought for agro-ecological models from the beginning. For instance, MODCOM can combine discrete and continuous simulation paradigms to handle management events during biophysical simulations.

MODCOM is also open-source and this grants for its full re-use within SEAMLESS.

On the down side, MODCOM has not a fully developed suite of applications (or framelets) as TIME and therefore adapting it for use to simulate biophysical models will be more labour intensive.

4.3.3 Contact details

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4.4 OpenMI

OpenMI stands for Open Modelling Interface and Environment, a standard for model linkage in the water domain. OpenMI is born as a product of the HarmonIT project, which aims at providing an infrastructure to unify and link models and tools for catchment management at a European scale. OpenMI consists of a set of software interfaces that allow new and existing models to interact with each other, with sources of data and with instruments and tools for the display and analysis of data.

In OpenMI a model can be regarded as an entity that can provide and/or accept data. OpenMI is based on direct access of the model at runtime, thus not using files for data exchange. A model is therefore implemented as a component, which can be accessed through a standard interface.

Parts of this review are based on the official OpenMI documentation, on an internal document provided by Alterra (Critical assessment of Open MI), and on a Review of OpenMI architecture reports A & B, by Dr Hamish Harvey (<http://www.cen.bris.ac.uk/pgra/dph/publications/2003-05-28-openmi1.pdf>).

4.4.1 Requirements matching

1. Uses declarative approach (formal representation of equations) for language independent model description (XML)

No. OpenMI is aimed at connecting existing models, which are 'black-boxes' wrapped up in a standard interface.

2. Knowledge-based support for modelling (e.g. advises users where coupling is appropriate)

Not implemented. Matching model interfaces and model composition is greatly enhanced by adopting the common OpenMI interface, but model teleology and semantics are not presently supported.

3. Framework software is open source (e.g. GPL)

The OpenMI software is supposed to be distributed as open-source.

4. Allows for quantitative (static, dynamic, stochastic, deterministic, descriptive, explanatory...), qualitative and conceptual components

The OpenMI interface is neutral with respect to the adopted modelling paradigm, since it concentrates on the data exchange. Yet, values are crisp and they are quantitative.

5. Supports both open and closed source submodels and tools

Yes. A model can be an opaque black-box, which simply implements the OpenMI interface, but a model can also be structured according to a 'template' provided by a class, which has methods such as initialise, and get_values, that contain the model code. The modeller is free to customise these methods and develop his/her own model implementation.

6. Version control for framework, components and scenarios

Not implemented.

7. Facilitates self-documentation

Yes. Each model has a description and an ID to facilitate model archival and retrieval.

8. Supports model and software quality checking

No formal method for model and software quality checking has been constructed within the OpenMI environment.

9. Allows web-based deployment of models and tools

This wasn't the focus of the development, but, being models implemented as components, it is easy to transform them into web services.

10. Supports a variety of different users

It supports model developers and model linkers. Finished applications, based on the OpenMI architecture, can be targeted to the end-users.

11. Provides repositories for: a) data / models; b) solvers; c) knowledge

While modelling knowledge is not explicitly supported, models can be stored for later usage, and the same holds for data visualisation and analysis tools.

12. Provides a benchmarking environment

Not available.

13. Portable between Linux and Windows

OpenMI is available in C# (runs on the .NET framework) and in Java, which runs on multiple platforms.

14. Allows development of packaged, customised applications

Yes. The component-based approach allows to package applications linking sub-models.

15. Models are reusable outside the framework

OpenMI reuses models provided by other frameworks. A model implementing the OpenMI interface can be re used by another framework which is compliant with that interface.

16. Can handle an evolving ontology (tag definitions)

The semantic annotation of model inputs and outputs is not available. Still there are three interfaces to describe what's returned from an OpenMI model IQuantity/IUnit/IDimension. OpenMI provides a warning mechanism that kicks in when things are obviously wrong. The terms "unit" and "dimension" are being used loosely.

17. Allows web-based publication of models and tools

Not explicitly, but it is easy to implement.

18. Allows specialised interactions between components (e.g. by using a workflow environment)

The OpenMI pull architecture favours model linking and reuse and components can be combined in a variety of ways. The OpenMI pull-model is expected to impose the least amount of restrictions in linking models: quantities are 'pulled' from models, which ask other models to provide what they need.

4.4.2 Potential contribution to SEAMLESS

OpenMI, as TIME, was originally intended for integrating catchment hydrology models. The basic principle behind OpenMI is that hydrological models are big, complex applications, and we therefore need a software framework to handle the hand over of data from application to application, not limiting to a simple pipeline, but also allowing for feedback loops. While OpenMI remains a framework for application linking, it also becomes very interesting to

provide a layer for integration of different SEAMLESS applications at various levels of scale, such as Economic Models at the European scale, with Farm-Economic models at the regional scale, and biophysical models at the field scale.

4.4.3 Contact details

Hyperlink: www.openmi.org

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Glossary

Application: it is a software package obtained from the modelling environment. An application includes a custom GUI and it includes several components.

Architecture: Blue-print and styles to define structure;

Component: it is a model of a physical piece of the system being built. For example, source code files, DLL's, Java beans and other discrete pieces of the system may be represented as components. By building the system in discrete components, localisation of data and behaviour allows for decreased dependency between classes and objects, providing a more robust and maintainable design. Components may be either models or tools/utilities.

Declarative code: computer code where the order of the statements is not relevant for its execution. Declarative code contains the model equations, but it does not tell how to compute a result using the equations. Modelling is an activity well suited to be described with declarative code.

Imperative code: computer code that explains how to solve a problem, following a unambiguous and definite sequence of steps. Imperative code processes declarative code. Simulation is an activity which requires imperative code.

Integrated framework: an application which allows the evaluation of agricultural systems accounting for technical, environmental, economic and social indicators. One or more integrated frameworks will be the main deliverables of the integrated project.

Model: focused simplification of (a phenomena or process in) the real world;

Modelling environment: a software which allows developing components and applications. The modelling environments contains components which include a GUI for either component or application development.

Legacy model: a model, often packaged in an application, inherited from someone else.

Modelling framework: the kernel component for static and dynamic model components use.

Ontology: it is a specification of a conceptualisation. Once a modeling exercise has defined all the variables and relationships existing in a given model, this information can be stored in an ontology. There are many languages which can be used to represent an ontology, but RDFS/OWL is one of the most common since, being based on XML, it can be easily processed by computers.

Project: when referred in the use cases of the user Application/component developer (see below) a project is either a component or a system model which includes several components. When the user is a farmer or a policy maker, a project is the use of an application in specific conditions (a farm, a region etc.)

Programming interface: a set of component interfaces, packaged in a binary object together with their implementations, with the necessary documentation to reuse them in a software application.

Proprietary model: a model for which the rights to access, use and inspect its code are limited by Intellectual Property Rights.

Simulation: monitoring dynamics of attributes (in time and/or in space);

Software framework: productivity tool(box) to assemble components using architecture

Open Source: software code for which you have complete access to the source code. Moreover, the source is freely usable and re-distributable under a license agreements such as GPL (Gnu Public License), LGPL and so on;

System: a portion of the real world, with clearly defined borders, described both in a static and dynamic fashion by models

Appendix 1. SEAMLESS requirements and suggested solutions

	Requirement	M S C W	P r i o r i t y	U r g e n c y	Simile	FIW	GF	Python	GCF	IMA	MODCOM	TIME
					r.muetzelfeldt@ed.ac.uk http://www.ferm.ed.ac.uk/simile/index.html	Framework for Integrated Watermanagement (but broader than water, so name will change soon) Tommy.Otjens@wur.nl Tamme.vanderwal@wur.nl	General Framework Tommy.Otjens@wur.nl Tamme.vanderwal@wur.nl	christophe.pradal@cirad.fr	CNC General Coupling Framework Griley@cs.man.ac.uk R.Warren@uea.ac.uk Tyndall centre http://www.cs.man.ac.uk/cnc-bin/cnc_gcf.pl	Integrating Modelling Architecture ferdinando.vilh@uvm.edu University of Vermont http://www.sf.net/projects/imt	Frits.vaneveri@wur.nl http://biosys.bre.orst.edu/modcom/index.htm	The Invisible Modelling Environment R.Argent@unimelb.edu.au Joel.Rahman@csiro.au www.catchment.crc.org.au
1	Uses declarative approach (formal representation of equations) for language independent model description (XML)	M - C	8	2	Simile has been developed specifically as a proof-of-concept demonstrator for a declarative modelling approach. Models are saved in an open text format: currently Prolog; we have a prototype converter to and from XML.	Yes / no. FIW is not explicitly build to support language independent model descriptions. You can however use wrapper around models that do.	Yes / no. GF uses XML to specify model meta-data. In this specification, only simple meta-data is provided to support the registration of the model within the GF.	Python provide tools for meta-modelling (AtoM3 , Basil). To define our own declarative approach we have to: 1 Design a language (mathematical modelling) Define an "Agronomic Markup language". AML (like XML or CML) might be though of as HTML with some agronomy added. Use parsers available from python: PyXML . These parsers will generate abstract syntax trees that are expressed in AML. AML will allow back end development in multiple environments due to the ease and ubiquity of AML parsing. Develop an engine to link together SEAMLESS components from the abstract language directives.	Our GCF (general coupling framework, see http://www.cs.man.ac.uk/cnc-bin/cnc_gcf.pl) system supports and promotes the flexible composition and deployment of coupled models. It uses XML to capture metadata describing (GCF-compliant - see below) models which are to be composed together, composition information describing how models will be coupled (in terms of their input and output requirements) and information regarding the required deployment (an appropriate set of) computational resources and communication mechanisms.	YES. The IMA is a modular, extendible object system where both classes and objects are specified in XML. XML-specified modules can represent data, models, optimizers, algorithms. Class implementers have a choice to leave some, all or none of the specification expressed as procedural or functional language fragments enclosed in CDATA sections. The IMA supports multiple modelling paradigms and is not by any means limited to equations as a way to describe a model. For modules whose specification requires equations (e.g. those whose state is calculated by integrating a differential equation), these can be specified entirely in XML if desired, although it is normally more intuitive to use some sort of expression of programming language. The IMA supports a full-fledged, object-oriented programming language and has plug-in support for other languages (Scheme, Javascript, Python, C/C++). Currently the modules implementing difference equation modelling, the STELLA importer (and probably the Simile importer that will be developed) use CDATA sections and the internal IMA language compiler rather than MathML or other XML-based ways to express the equations. Supporting MathML if required would require very little effort.	MODCOM components are defined at the binary level; such components can be written in a declarative language just as well as in Fortran, C/C++ or Java. Interaction with Robert Muetzelfeldt in May and December 2002 resulted in a proof-of-concept for the (automatic) translation of a Simile model to a MODCOM component.	TIME supports multi-language development within the .NET framework. Any requirements for model description (such as input and output definition, variable naming), are handled through formal metadata specification and utilisation.
2	Knowledge-based support for modelling (e.g. advises users where coupling is appropriate)	M	8	3	None at the moment. In the past we have developed a prototype built-in tutorial system, controlled by a marked-up tutorial file (which can be generated automatically from any Simile model). Also, strong links with AI going back 20 years on knowledge-based support	<i>Yes. FIW contains domain specific 'Model element'. The couplings between Model elements are predefined. It is easy to define new model elements and to specify allowable couplings.</i>	<i>No. Model applications have Accepting attributes and Providing Attributes. System builders can connect any providing attribute to any</i>	<i>Currently, we have developed amap-e-learning, an e-learning platform to accelerate knowledge transfer and facilitate learning AMAP technologies. There are</i>	Currently, our framework focuses on the mechanics of coupling models together and leaves the issues of scientific and numeric compatibility to the developer. We are aware of these issues and have submitted a grant proposal to investigate how far the capturing	YES. The IMA's primary goal is to give modellers the ability of using the bare conceptual bones of the problems while promoting a design discipline that automatically enforces constraints of semantics, space, time, and other applicable domains (e.g. consistency in	<i>Currently not, but this is envisioned to take place in layer 4 of the diagram below.</i> Caveat: enabling knowledge-based modeling support in MODCOM would not be difficult, but developing the expertise to support	The integral use of model metadata within the TIME environment supports the analysis of proposed model links through matching of data types. The lightweight architecture of the TIME core/kernel has the potential

	Requirement	M S C W	P r i o r i t y	U r g e n c y	Simile r.muetszel@ed.ac.uk http://www.ierm.ed.ac.uk/simile/index.html	FIW Framework for Integrated Watermanagement (but broader than water, so name will change soon) Tommy.Ojens@wur.nl Tamme.vanderwal@wur.nl	GF General Framework Tommy.Ojens@wur.nl Tamme.vanderwal@wur.nl	Python christophe.pradal@cirad.fr	GCF CNC General Coupling Framework Griley@cs.man.ac.uk R.Warren@uea.ac.uk Tyndall centre http://www.cs.man.ac.uk/cnc-bin/cnc_gcf.pl	IMA Integrating Modelling Architecture ferdinando.villa@uvm.edu University of Vermont http://www.sf.net/projects/imt	MODCOM Frits.vanever@wur.nl http://biosys.bre.orst.edu/modcom/index.htm	TIME The Invisible Modelling Environment R.Argent@unimelb.edu.au Joel.Rahman@csiro.au www.catchment.crc.org.au
					for modelling (the ECO project).		<i>accepting attribute.</i>	<i>courses, mailing lists, ...</i>	and incorporation of appropriate metadata can help with this problem (with appropriate domain experts).	measurement protocols or bibliographic source) - as well as the obvious constraints of storage type and units. Modules are tagged with semantic types (pointers into formally specified ontologies) and contain domain objects that represent cross-cutting aspects related to observation (space, time). Compatibility between all these is automatically enforced by specialized interfaces built over a common API. Domain types and ontologies can be added to the system in a plug-in fashion. The permanent storage functionalities and database interfaces have the ability of retrieving only semantics- and domain-compatible objects that will fit a precise role in an existing model structure. The domain functionalities are developed in the core engine and under implementation in the time and space domains. The semantic type functionalities are under development.	knowledge-based modeling would be a major effort.	to support any knowledge-based model support system that can be expressed in model metadata.
3	Framework software is open source (e.g. GPL)	M	4	2	At the moment, the core Simile software is partly compiled Prolog, and partly interpreted Tcl/Tk (text files, but not licensed as open source). However, any user can add their own input/output, display and run control tools ('helpers') in Tcl/Tk. Also, models themselves are totally open (see 1 above). Note: In the pure declarative modelling paradigm, there is no 'framework software'. There are only various documents (models/submodels plus various additional files such as scenario files and interface spec files), plus a collection of tools. Some tools may be gathered together to make a 'framework software' package, but this is not a necessary characteristic of the approach.	No. Source is available under conditions.	No. Source is available under conditions.	LGPL is better than GPL because you can mix open source and close source together.	Currently a version of the GCF system is available freely for academic use (see the web page above). Our University does not object to the software being made open source (probably under LGPL) at an appropriate time.	YES. Everything in the IMA is covered by the GPL, and there is no functionality that requires the use of closed-source software. This has been a main design goal for the IMA. All extensions use open source software (Mapserver/GEOS for GIS, R for statistics, PostgreSQL for permanent storage) although they can be implemented with commercial solutions if required.	Yes. Versioned source code is available at http://137.224.191.13/cgi-bin/cvsweb.cgi/	The CRCCH has a federal government requirement to assess the commercial potential of any CRC products. However, it is the intention of the CRCCH to distribute as much as possible of the system under an open source agreement. Licensing arrangements will be clarified over the coming months.
4	Allows for quantitative (static, dynamic, stochastic, deterministic, descriptive, explanatory...), qualitative and conceptual	M	4	1	Yes to all the above. Models begin life as flow/influence diagrams ("conceptual models"), and can be incrementally instantiated. Simile also supports qualitative variables (soil=clay/sandy/loam).	Yes. Any component that can produce values, can be used as a model for FIW.	Yes. Any component that can produce values, can be used as a model in the GF.	Yes. Python will be used as a software bus to link multi-language components together (C, C++, Fortran, Java, Python, R/Splus, Matlab, ...). Automatic wrappers are build from binary code and API. Unit	In principle any type of model is supported. The system is flexible. The current system has been developed with iterating/time-stepping scientific models in mind and "GCF compliance" is achieved by simply including calls to primitive put() and get() routines. If	YES. See point 1 for issues of modularity. Supporting a new modelling paradigm requires writing the correspondent XML class definitions and possibly some support methods using the C++ API.	Yes.	Yes. The TIME architecture has been designed to flexibly support a range of modelling methods and approaches. In line with CRCCH needs, the current models developments are almost entirely

	Requirement	M S C W	P r i o r i t y	U r g e n c y	Simile r.mueterfeldt@ed.ac.uk http://www.ierm.ed.ac.uk/simile/index.html	FIW Framework for Integrated Watermanagement (but broader than water, so name will change soon) Tommy.Ojens@wur.nl Tamme.vanderwal@wur.nl	GF General Framework Tommy.Ojens@wur.nl Tamme.vanderwal@wur.nl	Python christophe.pradal@cirad.fr	GCF CNC General Coupling Framework Griley@cs.man.ac.uk R.Warren@uea.ac.uk Tyndall centre http://www.cs.man.ac.uk/cnc-bin/cnc_gcf.pl	IMA Integrating Modelling Architecture ferdinando.villa@vtvm.edu University of Vermont http://www.sf.net/projects/imt	MODCOM Frits.vanevert@wur.nl http://biosys.bre.orst.edu/modcom/index.htm	TIME The Invisible Modelling Environment R.Argent@unimelb.edu.au Joel.Rahman@csiro.au www.catchment.crc.org.au
	components							test and documentation is added manually or semi-automatically. So, we can use quickly existing components for quantitative, qualitative and conceptual modelling.	this is unacceptable, we have techniques which enable models to be "wrapped" in a transformation wrapper which converts a models output to the required put() and get() model (dealing with any control issues - relating to whether the data exchange mechanism is a "push" or "pull" model. These have relatively simple control requirements. Models are composed using a dataflow approach. We are currently investigating handling more complex control structures.			quantitative.
5	Supports both open and closed source submodels and tools	M	3	2	Since Simile is a representative proof-of-concept demonstrator for declarative modelling, text is the natural format for representing models. This is intrinsically open-source, both for viewing and for editing. No doubt it is possible to engineer particular fixes (such as digital signatures) for particular software tools, but these would be specific to those tools. It would also be possible to have a declarative modelling approach that supports binary/encrypted files, but it would not, I think, get much support from tool developers and is certainly against the spirit of declarative modelling. Simile tools (input/output, display, run control) are written in Tcl/Tk, an interpreted language. They are thus open-source-viewable. Currently, they are not licensed for open-source-editing. There is no restriction on any Simile user developing their own tools.	Yes. Models can be delivered as a dynamic link library or executable or directly implemented in an FIW application.	Yes. Model applications can be provide as DLL or EXE. For each application a wrapper has to be written to make the application available to the framework.	Yes. Python is freely usable and distributable, even for commercial use. Components are loaded dynamically so closed source submodels can be used with open source one with respect of open source license requirement.	In principle both open and closed source models are allowed - see point 4.	YES. See point 4 and 1. Everything in the IMA can be plugged in as an extension and all software with a C API can be used. One specialized class of objects (working in previous versions, will need some work to update) handles interaction with closed executables, through proxy objects that range from command line drivers to CORBA/COM peers for enabled components. This allows legacy programs to be given the necessary semantic characterizations and wrapped at the executable level, becoming a component of a larger-scale model implemented in the IMA.	Yes.	Yes. Through multi-language support and the capabilities of the .NET system, TIME supports linking with compatible open and closed sources models and tools. In addition, a proposed development in cooperation with the European Open Modelling Interface (OpenMI) (www.harmonit.org) will increase the linking capabilities of TIME with a range of European hydraulic and hydrological models.
6	Version control for framework, components and scenarios	M	3	1	All aspects of Simile are suitable for version control. (We make extensive use of CVS in Simulistics.)	No. The framework itself and the applications written using the framework, are stored in CVS.	No. The framework itself and the application and components are stored in a Visual Sourcesafe database. Support is managed by the company MX-Systems in Rijswijk (NL)	Yes. CVS (Concurrent version system) is a widely used system for open source software. It is easy to use (lots of GUI frontends) and support many developers.	This issue is considered to be external to the GCF itself. We currently use CVS and our clients also use CVS for their model code (which is not in any sense "owned" by the GCF system).	UNDER DEVELOPMENT. The permanent storage interface allows version control and specialized, XML-specified "difference" objects are planned that can be applied to other objects to modify them. This is a central feature to enable a "bulletin-board" approach where the objects of discussion are actual data and models - one central goal for the IMA and the projects it's currently at the center of.	Yes. Versioned source code is available at http://137.224.191.13/cgi-bin/cvsweb.cgi	Framework and component development uses CVS for version control. No formal control of scenarios has been implemented.
7	Facilitates self-documentation	M	2	3	This is a major strength of declarative modelling. The combination of an ontology	No. It is not difficult to extend FIW with reporting tools to generate documentation about	No. Not supported.	In the standard Python library, there are several tools to extract and process	The framework generator software is basically Java and XML processing technology so JavaDOC	YES. The core IMA engine has a template-based self-documentation system that uses templates to	MODCOM components are defined at the binary level; MODCOM wants components to do their job	Yes. The metadata capabilities of both TIME and .NET support a

	Requirement	M S C W	P r i o r i t y	U r g e n c y	Simile r.mueterzfeldt@ed.ac.uk http://www.ierm.ed.ac.uk/simile/index.html	FIW Framework for Integrated Watermanagement (but broader than water, so name will change soon) Tomny.Oijens@wur.nl Tamme.vanderwal@wur.nl	GF General Framework Tomny.Oijens@wur.nl Tamme.vanderwal@wur.nl	Python christophe.pradal@cirad.fr	GCF CNC General Coupling Framework Griley@cs.man.ac.uk R.Warren@uea.ac.uk Tyndall centre http://www.cs.man.ac.uk/cnc-bin/cnc_gcf.pl	IMA Integrating Modelling Architecture ferdinando.villa@vtvm.edu University of Vermont http://www.sf.net/projects/imt	MODCOM Frits.vanvert@wur.nl http://biosys.bre.orst.edu/modcom/index.htm	TIME The Invisible Modelling Environment R.Argent@unimelb.edu.au Joel.Rahman@csiro.au www.catchment.crc.org.au
					specifically developed for modelling (compartments, flows, submodels), plus user-supplied labels (biomass), makes it straightforward to automatically generate meaningful descriptions ("the model has a compartment called biomass"). Additionally, extra markup can be provided for any model element, and directly associated with that element. A demonstration HTML generator has been developed for Simile models.	a used schematization.		documentation and self-documentation. For example, Pyfindoc is a tool like Javadoc: it generate documentation for source code comment.	is a practical approach for documenting the code. The XML files describing the definition, composition and deployment (DCD) aspects can be viewed in user accessible ways using tools, for example, XMLSpy.	enable self-documentation of objects in formats such as HTML, text, or LaTeX. This system is currently used for all web-enabled database applications based on the IMA. Plug-in support for MIME types can be also plugged in on a class-specific basis. This feature is used to allow objects to intelligently select their proper multimedia representation given a MIME type (e.g. spatial objects will generate GIS maps, temporal objects will generate timeseries graphs, and spatio-temporal objects will generate animated maps, all as an answer to the same request for a image/png).	but doesn't care how they do it. A component could make available the (declarative?) specification of the model it represents and documentation could be generated from that.	reasonable level of self-documentation (assuming developers provide correct metadata and required fields when coding)
8	Supports model and software quality checking	M	2	3	Simile's interactive model-design environment contains numerous tests for errors in model development (e.g. equation syntax). Additionally, a number of aids have been developed to support debugging of complex models (such as mouse-over to show the current value of any model element, and a snapshot tool to freeze such values). Other tools are being planned. Also, any submodel can be saved as a stand-alone model, for independent testing. Software (in the sense of code for model execution) is automatically generated: the source code is available for inspection.	No. There are tools to generate and visualize model output.	No. There are tools to generate and visualize model output.	Python community provide framework for quality checking: 1. Unit test framework (PyUnit , unittest or doctest) 2. Source code checking (PyChecker , Pylint) 3. Python debugger (pdb) 4. Python profiler (profile) Each components have to provide interface documentation and unit test at least. Before each release, we can check the quality of the SEAMLESS platform by testing all the components.	This is considered to be external to the GCF system.	UNDER DEVELOPMENT. Storing accuracy information along with data and model is a crucial feature in an environment that allows arbitrary composition of data sources and processing algorithms (with associated compounding of error) and allows automatic rescaling of differently scaled information (with associated transformation error). Such features are not implemented in the IMA at this time, and one of the projects where the IMA concepts are being used (SEEK: http://seek.econinformatics.org) has a working group that is tackling these complex issues.	MODCOM components are defined at the binary level; at that level, one is past the checking of model and/or software quality. But there are many ways in which quality checks could be supported. A component could provide information about valid ranges for inputs; a checking component could be written to signal when those ranges are exceeded. A component could make available the (declarative?) specification of the model it represents; checks could be made on the basis of it.	No formal method for model and software quality checking has been constructed within the TIME environment.
9	Allows web-based deployment of models and tools	C	2	3	Models can be deployed in XML. A test version of Simile has demonstrated that models can be easily downloaded from the web by clicking on a link. Indeed, a model can be constructed in a minute or two by clicking on submodels with different URLs. Tools (input/output, display and run control) can be distributed as text files (but not currently loaded by clicking links).	No. FIW applications are self contained, to add new models, you have to extend the application with new model elements and attributes.	Yes. The generic framework uses registerable modules.	It is possible with Webware . an open source suite of software components for developing object-oriented, web-based applications.	The framework support flexible deployment and Web/Grid services is one of the deployment areas we support. The flexibility allows a composition of a set of GCF models to be deployed on resources ranging from a single machine, through a dedicated parallel machine through the Grid, using a suitable mpi, through to Web and eventually Grid services.	YES. This is a core requirement for all the projects that the IMA is currently employed in. A specialized IMA runtime runs as a multi-user server and a CGI IMA client allows full control of an IMA object database and hierarchy through the web. The self-documentation engine does the rest, allowing complete deployment of models, data, and analysis tools.	Currently no facilities, but I can't think of a reason why MODCOM-based components and tools couldn't be deployed through the Web.	Yes. Models and tools will become progressively available from www.toolkit.net.au over the next three years.
10	Supports a variety of different users	M	2	2	Simile has been developed for research-grade modelling. However, its intuitive user interface allows it to be used by total	Yes. Modelers extend the application by programming. System builders create	Yes. Modelers build Model applications. System builders can	Yes.	No reason why not. This is really an issue for the GUI or portal which is considered to be beyond	YES. IMA-enabled applications can be used as simple databases from the Web while modellers can use the IMA as an XML modelling	Yes.	Yes. We currently identify 5 major user types, and consider the requirements of



	Requirement	M S C W	P r i o r i t y	U r g e n c y	Simile	FIW	GF	Python	GCF	IMA	MODCOM	TIME
					r.muozfeldt@ed.ac.uk http://www.iERM.ed.ac.uk/simile/index.html	Framework for Integrated Watermanagement (but broader than water, so name will change soon) Tommy.Oijens@wur.nl Tamme.vanderwal@wur.nl	General Framework Tommy.Oijens@wur.nl Tamme.vanderwal@wur.nl	christophe.pradal@cirad.fr	CNC General Coupling Framework Griley@cs.man.ac.uk R.Warren@uea.ac.uk Tyndall centre http://www.cs.man.ac.uk/cnc-bin/cnc_gcf.pl	Integrating Modelling Architecture fernandovilla@uvm.edu University of Vermont http://www.sf.net/projects/imt	Frits.vanever@wur.nl http://biosys.bre.orst.edu/modcom/index.htm	The Invisible Modelling Environment R.Argent@unimelb.edu.au Joel.Rahman@csiro.au www.catchment.crc.org.au
					novices. Customised user interfaces for running the model (and hide the model structure) can and have been readily developed. In fact, we have a simple (and declarative) user-interface description language that allows any user to develop customised interfaces using elements like slider, graph and labels, even sound and animated gifs, to display model behaviour.	schematizations that are stored in a database. End users can load schematizations and run scenarios.	build and run systems.		the scope of GCF itself.	tool and runtime environment. Different runtimes can be created very simply using policy-based design, supporting batch modelling, client/server interaction, or GUI interaction (currently not implemented).		each.
11	Provides repositories for: a) data / models; b) solvers; c) knowledge	M	1	2	Models can be stored in regular or XML databases (e.g. ColdFusion). There is no direct access to databases at the moment, but this is planned. Solvers are currently built into the Simile framework (this is mainly due to the fact that Simile models can have a far more complex state variable structure than conventional modelling environments, so making it difficult to have a general external mechanism for having external numerical integration routines.) The knowledge associated with any model element can be saved with it (as comments), and retrieved on request. This could be marked up in e.g. XML syntax. We have also experimented with allowing an arbitrary number of URLs to be associated with a model element, enabling a user to tap into unlimited resources on the web about (for example) a sheep submodel, the Penman-Monteith equation, or whatever.	No	Yes. Models and tools are registered in the framework. You don't need to rebuild the application to add new models or tools.	Not currently. These tools are envisioned in layer 4 of the diagram above.	These are considered to be beyond the scope of the GCF system itself but we have a proposal for funding submitted to begin to address this provision.	YES. (see points above, too).The IMA runtime has a virtual repository interface that uses XML-specified views and queries. It has been currently implemented on top of PostgreSQL out of consideration of stability, open source and availability of specialized spatial operator. A native XML implementation based on Apache's XIndex may be the next priority. All of the three classes of objects mentioned in the requirement map into representational categories handled by the IMA and its permanent storage system.	Not currently. These tools are envisioned in layer 4 of the diagram above.	yes. The toolkit website has been identified as our primary repository. At present no specific solvers have been developed within TIME. However, these would be handled similarly to a), above. c) We are developing both an information management system for the Toolkit, and a "toolkit assistant" that will act as the primary model knowledge system.
12	Provides a benchmarking environment	M	1	2	Simile currently provides very limited tools for exploring model behaviour - essentially, simple simulation. However, run controls are separate plug-ins, and can be independently developed for (e.g.) sensitivity analysis, replicate runs, and benchmarking.	No.	No.	<i>Not currently. Envisioned in layer 4.</i>	Beyond the scope of GCF	I'm afraid I know too little about the meaning of this requirement in the SEAMLESS context to answer. In general the explicit semantics of IMA modules allows many metrics to be calculated on them (e.g. the runtime system can estimate the resource requirements of a model by its representation, and enforce hard constraints on it before trying to allocate and run it).	Not currently. Envisioned in layer 4.	We have benchmarking tools for TIME development, but little development has been undertaken for model benchmarking.
13	Portable between Linux and Windows	M	1	3	Microsoft Windows 98, Me, NT, 2000 and XP are all supported. Linux and FreeBSD (x86 architecture), and SunOS (Sparc	<i>No. FIW is written in Delphi, maybe an adapted Kylix version could run on Linux.</i>	No. Generic framework is written in Delphi, maybe an adapted Kylix	<i>Yes. Python, tools and frameworks used to design SEAMLESS architecture are portable. To be added with</i>	The GCF system supports flexible deployment including platform OS. Currently we have been experiencing problems with our	YES (potentially). The IMA is written in ANSI C++ and has no dependence on particular OS architectures. On the other hand, all	<i>Yes, in principle; although in practice it is probably more trouble than it's worth. Biggest problem areas would be with C++'s</i>	.NET is currently Windows based. Open source development of the Linux equivalent (Mono www.go-



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					architecture) are all supported. Active development for Apple OS X is underway (in beta test).		version could run on Linux.	<i>SEAMLESS, components have to distribute a shared library (so and dll) on Linux and Windows. Then, SEAMLESS platform will be portable.</i> <i>For Linux available components, we can use Cygwin to port them on Windows. And for windows ones, we can use WinLib.</i>	Globus deployment on windows but we believe the use of Cygwin overcomes these and are currently testing this.	the development has been done on Linux and I had no interest so far in porting it to Windows (particularly because the chief mode of interaction has been through a Web browser, thus OS-independent). I see no reason why porting to Windows should be a problem, particularly if using a Cygwin environment, but it has not been attempted so far.	<i>standard template library (of which many implementations exist) and with variant support on Linux. There are solutions (e.g. Wine for variants) but they don't always work quite the way one would like.</i> Best option for portability might be that at some point in the future MODCOM will be ported to the .NET environment, for which a runtime environment will also be available on Linux.	mono.com) offers potential for Linux deployment.
14	Allows development of packaged, customised applications	M	1	2	Yes: see 10 above.	<i>Yes. FIW is a programmers framework, it is used to build domain specific simulation applications.</i>	No. Generic framework is a complete system for building and running simulations.	<i>Yes. Tools and methodology to manage the release of a large project are described here.</i>	No reason why not.	YES/IN DEVELOPMENT. IMA models can be executed by a runtime and it's easy to package a model with its own runtime system. A feature in development (low priority at this time) is the translation of a whole model into C language for compilation and delivering as an executable.	Yes.	Yes. The component-based approach used with TIME supports development of tailored user interfaces for collections of components linked together to form specific modelling solutions.
15	Reusable outside the framework	M	-	3	Simile models represented in XML format can be processed by any tool capable of handling XML. This includes all programming languages with an XML API, and XSLT. Models can also be converted into Prolog and processed with Prolog's far more powerful engine for symbolic reasoning. Generated C++ source code can be hand-integrated into other systems. Compiled DLLs can be integrated into other systems directly (this has been done by the SimArc group in the University of Naples).	Yes / No. Maybe FIW applications can run as a batch or as a COM component, but is not designed to do so.	No.	Yes.	A principal aim of the system! A GCF-compliant model should be able to be used in any framework through the use of an appropriate and simple to generate wrapper. We currently support a number of deployment options (see above, point 9) which demonstrate this principle.	YES. IMA modules are executed by a runtime that can assume many different forms and be hosted on a local computer or a server. Policy-based software design allows the runtime operation to be redefined in a very simple way.	Yes.	What is re-usable? Packaged customised applications are re-usable. Generally, TIME components (packaged as DLLs) are not reusable.
16	Can handle an evolving ontology (tag definitions)	M	-	2	The Simile XML Schema is currently rather fluid (the Prolog format is still Simile's native model-representation format). As it matures, we plan to introduce namespaces (at least two: one for System Dynamics elements, one for the object-based aspects, possibly using XML). Additionally, MathML might be used for mathematical expressions, but this will considerably increase the size of file. However, even if there were only a single Simile Schema, it would still be possible for the Schema to be extended, or for a	Yes - but you have to extend the model elements programmatically.	Yes / No. The generic framework adapts easily to extended model applications.	Yes.	Although this is outside the scope of what we have achieved so far, we consider it to be part of the scientific compatibility issues for which funding has been requested to address.	IN DEVELOPMENT. IMA modules can be tagged with semantic types that point to specific ontologies. The issue of tracking evolving ontologies without losing semantic integrity is, anyway, extremely tricky and how to deal with it is not well understood in general. One of the projects that the I and the IMA concepts are involved in (SEEK, mentioned above) has a Semantic Mediation and a Knowledge Representation working group that is discussing how to deal efficiently with	Yes. MODCOM is based on interfaces – components can always implement another interface through which additional functionality can be made available. Existing components could be "retrofitted" by aggregating or compositing them.	Possible through evolution of TIME metadata definition and utilisation.



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					group (e.g. SEAMLESS) to add their own namespace.					evolving semantics.		
17	Allows web-based publication of models and tools	M	-	2	Yes. Models will be published as XML documents. These will be viewable through a variety of XSLT filters. Or as documents generated (by XSLT) from the raw XML. (What is meant by publication of tools?)	No.	No.	Yes. Easily.	Yes. See above.	YES. This question has been extensively answered in many of the above points.	Currently no facilities, but I can't think of a reason why MODCOM-based components and tools couldn't be published through the Web.	Yes. See (9) above.
18	Allows specialised interactions between components (e.g. by using a workflow environment)	M	-	2	No modelling workflow environment developed.	Yes. Programmers have access to every aspect of the Model elements, their attributes and their sources. Specialized access should be reduced as much as possible. If specialized access is needed, effort should be put in extending or defining new access methods that are more generalized.	No. Access between components is only done through connectors.	Yes. Through the python language.	This is not currently supported - see point 4.	YES. The IMA is a workflow environment by its own nature and is highly customizable.	Yes.	TIME supports the development of tailored components interactions through metadata manipulation.
	Additional comments				Declarative modelling can potentially be integrated with component-based modelling architectures in 3 main ways. First, a declarative modelling tool like Simile can be used to produce individual components. Second, a declarative modelling environment can include programmed components (this is in effect what the Tyndall Centre's integrating framework does, with XML wrappers for each component, and the complete model specified as an XML document.). Third, component-based architectures can provide components for many support tasks (links to GIS, running simulations, etc), with the model itself being a single component (either programmed or produced in a declarative modelling environment). Therefore, it is possible to envisage ways of combining a declarative approach with a component-based approach. However, even if both the first and second methods are used in the previous point (i.e. components are specified declaratively, and the component structure of the model is represented declaratively), there are	FIW is a programmers' tool used within WISL for designing integrated applications and producing source code. A Delphi objects library is used to manage and link components e.g. FORTRAN-derived dlls. FIW has now been used for 4-5 years, and 4 key applications have been developed by WISL's water and environment group.	GF is a wide Dutch initiative used by e.g. Delft Hydraulics, Alterra, WISL. It is based on FIW concepts but is an end-user environment, used for configuration and building models. A graphical interface allows users to connect modules and define data passes.	Python is an interpreted, interactive, object-oriented programming language. It combines remarkable power with very clear syntax. It has modules, classes, exceptions, very high level dynamic data types, and dynamic typing. There are interfaces to many system calls and libraries, as well as to various windowing systems (X11, Motif, Tk, Mac, MFC). New built-in modules are easily written in C or C++. Python is also usable as an extension language for applications that need a programmable interface. The Python implementation is portable (UNIX, Windows, Mac...) and freely usable and distributable, even for commercial use.	The Tyndall project is the design, construction and application of an integrated modelling system to aid decision makers considering the potential human response to the climate change problem. In order to build the modelling system, we required the technical capability to construct a flexible, modular and distributed integrated modelling system. Modularity is necessary in order that the modelling system can be configured in different ways, so that models can "plug and play" within the system; flexibility is necessary in order to answer a range of evolving policy questions; and a distributed nature is required in order to take advantage of the full range of modelling capabilities at different institutions in Europe which address the relevant disciplines (for us, climatology, economics, and climate impacts on natural and human systems). The system which we chose to provide these capabilities is the GCF, general coupling framework, built by the Centre for Novel Computing (CNC) at the University of Manchester.	MODCOM's central concept is that of well-defined, self-describing component models, either written specifically for MODCOM or included through an adapter. A MODCOM simulation is constructed as a collection of interconnected components. MODCOM's component architecture provides a robust base for building flexible, domain-specific tools for such tasks as visual construction of components and simulations, specification of spatial relationships, and optimization. The MODCOM core functionality has been implemented (layer 1 and layer 2 in diagram below). A number of agro-ecological process components have been developed (layer 3). In Wageningen, we have developed a tool for visual construction of simulation models (layer 4); another such tool has been developed in Oregon; both still need further development.	The Invisible Modelling Environment (TIME) is a new environmental modelling framework being developed within the Catchment Modelling Toolkit project in the CRC for Catchment Hydrology. TIME differs from existing modelling frameworks in a number of ways, particularly in its use of metadata to describe and manage models as well as the flexibility given to model developers to 'pick and choose' the components of TIME relevant for a given project. Functionality that is embedded as an immutable 'core' layer in other frameworks is included in applications under TIME on an as-needed basis using optional, interchangeable components. This flexibility extends to components that manage data and models, recognising that one approach does not necessarily fit all applications. TIME includes a number of small framelets	

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					<p>still significant problems with a component-based approach. These relate mainly to the problem of rigid interfaces, and to technical issues concerned with the sequencing of component execution.</p> <p>3. A commitment to declarative modelling does not imply a commitment to Simile. Other architectures (IMA) support declarative modelling to some extent, including notation for representing System Dynamics models. Moreover, Simile could be used as a short-term gap-filler while other tools are developed within the consortium. The investment in model development will be preserved provided that the consortium tools have at least the expressiveness of Simile.</p>			<p>A large number of extension modules have been developed for Python. Some are part of the standard library of tools, usable in any Python program (e.g. the math library and regular expressions). Others are specific to a particular platform or environment (e.g. UNIX, IP networking or X11) or provide application-specific functionality (e.g. image or sound processing).</p> <p>Python also provides facilities for introspection, so that e.g. a debugger or profiler for Python programs can be written in Python itself. There is also a generic way to convert an object into a stream of bytes and back, which can be used to implement object persistency as well as various distributed object models.</p> <p>Our proposal for the SEAMLESS architecture is to develop a multi-language component platform based on a declarative approach, specific to SEAMLESS. We will glue together different python based frameworks and multi-language components (C, C++, Fortran, Java, R/Splus, Matlab, ...) to obtain a flexible and scalable open source architecture.</p>	<p>CNC and Tyndall are collaborating together to connect computer modules from different institutions within the UK and Europe using the general coupling framework. We have recently completed a prototype global-scale Community Integrated Assessment Model (CIAM) which we are continuing to expand.</p> <p>Like yourselves, we have a need to integrate across issues, disciplines and scales. We will therefore be nesting regional and local modules within the global modelling system that has thus far been assembled. Within this context, we do have an interest in Europe and in the complex inter-relationships between climate change, land use change and agriculture. Therefore, there is scientifically an advantage in making our systems compatible. We also have a parallel participatory process involving stakeholders.</p> <p>On the technical side, many of our requirements are similar to yours. We require the declarative approach between modules; we have a need to integrate quantitative and qualitative information; we require application to both Unix and Windows environments; and we will need to accommodate both open and closed source modules within the system; and version control is of course a standard need.</p>		<p>Several of the requirements listed below pertain to functionality in layer 4. As may be clear from the above, we strongly believe that such functionality is best implemented on the foundation provided by layers 1 through 3.</p>	<p>supporting extension in key areas such as data representation and visualisation. All fundamental data types, such as rasters and time series, are defined within the data framelet, which supports the definition of new, compatible data types. The visualisation framelet allows the definition of 'layers', each providing a visual representation of some type of data, such as rasters or polygons. Multiple layers can be placed on a single 'view', such as overlaying a polygonal map on a raster. Views can be surrounded by 'decorators' such as axis and titles, each of which can be combined independently. TIME includes a number of tools, which operate generically on models, including an automatic user interface generator and various model optimisation tools. TIME is developed on the Microsoft .NET platform and supports the development of models in a variety of languages, including Visual Basic.NET, Fortran 95.NET, C# and Visual J#. TIME is currently being used to develop a range of modelling applications, including a library of rainfall runoff models and a model supporting assessment of stream ecosystem health under various flow scenarios.</p>