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Maximum likelihood estimation of the GLS model with unknown parameters in the disturbance covariance matrix.

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Maximum likelihood estimation of the GLS model with unknown parameters in the disturbance covariance matrix.

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#### 1. Introduction

In this paper we consider the regression model  $y = X\beta + \epsilon$  with all the classical assumptions (including normality) but one, viz. we assume that the covariance matrix of the disturbances depends upon a finite number of unknown parameters  $\boldsymbol{\theta}_1 \dots \boldsymbol{\theta}_m.$  If the parameters  $\boldsymbol{\theta}_1 \dots \boldsymbol{\theta}_m$  were known, the Aitken estimator would be the BLU and maximum likelihood estimator. Since we assume that the  $\theta$ 's are unknown, we are faced with the problem to estimate the  $\beta$ 's and the  $\theta$ 's simultaneously. In sections three and four we derive the first and second order conditions and the information matrix for the ML estimators of  $\beta$  and  $\theta$ . These appear to be surprisingly simple. The next two sections are devoted to the properties of the ML estimators and to an algorithm that leads, under general conditions, to a solution of the ML equations. In section seven we apply these formulae to a general case, which facilitates the derivation of the ML estimators and the information matrix in the last two sections which are devoted to the autocorrelated errors model and to Zellner-type regressions. It is known from the literature that iterative Zellner and iterative Cochrane-Orcutt are equivalent with the ML estimates. In the present paper these iterative estimators appear as corollaries of much more general cases.

I wish to express my gratitude to prof H. Neudecker, who advised and encouraged me in this research. I am also indebted to R.D.H. Heijmans for stimulating discussions on the statistical part of this paper.

#### 2. The "vec"-function and the Kronecker product

Let  $A = [a_{ij}]$  be an (m,n) matrix<sup>1)</sup> and  $A_{ij}$  the jth column of A, then vec A is the (mn) column vector

$$\text{vec } A = \begin{pmatrix} A & 1 \\ \vdots & A & D \end{pmatrix}.$$

Let further Q be an (s,t) matrix, then the Kronecker product A @ Q is defined as the (ms,nt) matrix

$$A \otimes Q = [a_{ij}Q].$$

An important connection between the vec-function and the Kronecker product is 2)

$$vec ABC = (C' \otimes A) vec B,$$
 (1)

where A is (m,n), B is (n,p) and C is (p,q).

Special cases of (1) are

vec AB = (
$$I_p \otimes A$$
) vec B = (B'  $\otimes I_m$ ) vec A = (B'  $\otimes A$ ) vec  $I_n$ . (2)

The basic connection between the vec-function and the trace is

$$tr AZ = (vec A')'(vec Z),$$
(3)

where Z is an (n,m) matrix.

From (3) we derive the more complicated expressions

where D is a (q,m) matrix.

We now use (4) to establish the most general formula

tr ABCEF = (vec E')'(C' 
$$\otimes$$
 FA)vec B = (vec E)'(FA  $\otimes$  C')vec B', (5)

where E and F are matrices of orders (q,r) and (r,m) respectively.

<sup>1)</sup> A matrix of order (m,n) is one having m rows and n columns.

A collection of theorems on Kronecker products and matrix differentiation has been given by Neudecker (1969).

For easy reference we state the following special case of (4):

$$tr GVHV = (vec G)'(V \otimes V)vec H,$$
(6)

where G,H and V are symmetric matrices. Finally,

$$x'AB = (\text{vec A})'(B \otimes x) = (\text{vec A'})'(x \otimes B), \tag{7}$$

where x is an (m,1) vector.

#### 3. The maximum likelihood equations

Consider the linear regression model

$$y = X\beta + \varepsilon,$$
 (8)

where y is an(n,1) vector of observations on the dependent variable, X is an(n,k) matrix of the values of the regressors,  $\beta$  is a (k,1) vector of the regression coefficients, and  $\epsilon$  is an(n,1) disturbance vector. We shall make the following assumptions:

ASSUMPTION 1:  $\epsilon$  is normally distributed .

ASSUMPTION 2:  $E_{\epsilon}=0$ ,  $E_{\epsilon\epsilon}'=\Omega$ , where  $\Omega$  is a positive definite (hence nonsingular) matrix whose elements are twice differentiable functions of a finite and constant number of parameters  $\theta_1, \theta_2, \dots, \theta_m$ , i.e.  $\Omega=\Omega(\theta)$ ,  $\theta \in \Theta$ .

ASSUMPTION 3: X is a fixed matrix of full rank and n > k.

ASSUMPTION 4: The parameters in  $\beta$  are independent from those in  $\theta$ .

#### Theorem 1

The linear regression model (8) under the assumptions (1)-(4) has the following first-order ML conditions

(i) 
$$\hat{\beta} = (x'\hat{\Omega}^{-1}x)^{-1}x'\hat{\Omega}^{-1}y$$
 (9)

(ii) 
$$\operatorname{tr}\left(\frac{\partial\Omega^{-1}}{\partial\theta_{h}}\right)_{\theta=\widehat{\theta}} \widehat{\Omega} = e^{i}\left(\frac{\partial\Omega^{-1}}{\partial\theta_{h}}\right)_{\theta=\widehat{\theta}} e$$
, where  $e=y-X\widehat{\beta}$ . (10)

Further if  $|\Omega|$ , the determinant of  $\Omega$ , does not depend upon  $\theta_j$ , the jth equation in (10) reduces to

$$e'\left(\frac{\partial \Omega^{-1}}{\partial \theta_{j}}\right) = \hat{\theta} = 0$$
.

<sup>3)</sup> Assumption 4 can be relaxed. See Magnus (1977a)

The probability density of y takes the form

$$(2\pi)^{-n/2} |\Omega|^{-\frac{1}{2}} \exp -\frac{1}{2} \epsilon' \Omega^{-1} \epsilon$$
.

Let  $V=\Omega^{-1}$ , then the loglikelihood is

$$\Lambda = \gamma + \frac{1}{2}\log|V| - \frac{1}{2}\epsilon'V\epsilon, \tag{11}$$

where  $\gamma = -\frac{n}{2} \log \, 2\pi$  is a constant. Differentiating  $\Lambda$  we have  $^4)$ 

$$d\Lambda = \frac{1}{2} \text{tr} V^{-1} dV - \epsilon' V(d\epsilon) - \frac{1}{2} \epsilon' (dV) \epsilon$$

$$= \epsilon' V X(d\beta) + \frac{1}{2} \text{tr} (V^{-1} - \epsilon \epsilon') (dV). \tag{12}$$

Necessary for a maximum is that  $d\Lambda=0$  for all  $d\beta\neq 0$  and  $d\theta\neq 0$ . Thus:

(i) 
$$\epsilon'VX = 0$$

(ii) 
$$\operatorname{tr}(V^{-1} - \varepsilon \varepsilon') \frac{\partial V}{\partial \theta_h} = 0$$
 (h=1...m),

which proves the first part of the theorem.

Now suppose that |V| does not depend upon  $\theta_{i}$ , then

$$0 = \frac{\partial \log |V|}{\partial \theta_{i}} = trV^{-1} \frac{\partial V}{\partial \theta_{i}} , \text{ which proves the second part.} \quad \Box$$

It will be convenient to write (12) explicitly as a function of d $\beta$  and d $\theta$ .  $tr(V^{-1}-\epsilon\epsilon')(dV) = [vec(V^{-1}-\epsilon\epsilon')]^{-1}$  vecdV

= 
$$\left[\operatorname{vec}(V^{-1} - \varepsilon \varepsilon')\right] \cdot \left(\frac{\partial \operatorname{vec}V}{\partial \theta}\right) \cdot d\theta$$
.

It follows that

$$d\Lambda = (d\beta)'X'V\epsilon + \frac{1}{2}(d\theta)'\left(\frac{\partial \text{vec}V}{\partial \theta}\right) \text{vec}(V^{-1} - \epsilon \epsilon') . \tag{13}$$

#### Remark

We shall refer to equation (10) as the  $\theta$ -equation(s).

In what follows we shall use the definition of a matrix derivative as in Neudecker (1969). For instance the expression  $\partial \text{vecV}/\partial \theta$  describes an  $(m,n^2)$  matrix.

# 4. Derivation of the Hessian matrix and the information matrix

We recall from (11) and (13) that 
$$\Lambda = \gamma + \frac{1}{2} \log |V| - \frac{1}{2} \epsilon' V \epsilon , \text{ and }$$
 
$$d\Lambda = (d\beta)' X' V \epsilon + \frac{1}{2} (d\theta)' \left( \frac{\partial \text{vec} V}{\partial \theta} \right) \text{ vec}(V^{-1} - \epsilon \epsilon').$$
 Now, 
$$d^2 \Lambda = \left[ (d\beta)', (d\theta)' \right] H \begin{bmatrix} d\beta \\ d\theta \end{bmatrix}.$$

The structure of H is given by the following theorem.

#### Theorem 2

Define the symmetric (m,m) matrices

$$M^{ij} = \frac{\partial \Omega^{-1}_{ij}}{\partial \theta \partial \theta'} \qquad (i,j=1...n)$$
(14)

and let  $\Omega = \left[\omega_{ij}\right]$ , then the Hessian matrix of the loglikelihood function (11) is

$$H = \begin{bmatrix} H_{11} & H'_{12} \\ H_{12} & H_{22} \end{bmatrix}$$
 , with

$$H_{11} = -X'\Omega^{-1}X$$

$$H_{12} = \left(\frac{\partial \text{vec}\Omega^{-1}}{\partial \theta}\right) \quad (X \otimes \varepsilon)$$

$$H_{22} = \frac{1}{2} \sum_{i,j} (\omega_{ij} - \varepsilon_i \varepsilon_j) M^{ij} - \frac{1}{2} \left( \frac{\partial \text{vec} \Omega^{-1}}{\partial \theta} \right) (\Omega \otimes \Omega) \left( \frac{\partial \text{vec} \Omega^{-1}}{\partial \theta} \right)'.$$

#### proof

Starting from (13) we have 
$$d^{2}\Lambda = (d\beta)'X'V(d\epsilon) + (d\beta)'X'(dV)\epsilon + \frac{1}{2}(d\theta)'d\left(\frac{\partial \text{vec}V}{\partial \theta}\right)\text{vec}(V^{-1}-\epsilon\epsilon') + \frac{1}{2}(d\theta)'\left(\frac{\partial \text{vec}V}{\partial \theta}\right)d \text{vec}(V^{-1}-\epsilon\epsilon')$$

$$= -(d\beta)'X'VX(d\beta) + (d\beta)'X'(dV)\epsilon + \frac{1}{2}(d\theta)'d\left(\frac{\partial \text{vec}V}{\partial \theta}\right)\text{vec}(V^{-1}-\epsilon\epsilon') + \frac{1}{2}(d\theta)'\left(\frac{\partial \text{vec}V}{\partial \theta}\right)d \text{vec}(V^{-1}-\epsilon\epsilon')$$

From the definition of M<sup>ij</sup> in (14) it follows that

$$\begin{split} \mathrm{d} \left( \frac{\partial \mathrm{vec} V}{\partial \theta} \right) &= \left[ \mathrm{M}^{11} \mathrm{d} \theta \,, \mathrm{M}^{12} \mathrm{d} \theta \,, \ldots, \mathrm{M}^{\mathrm{nn}} \mathrm{d} \theta \right] \,, \, \, \mathrm{so} \,\, \mathrm{that} \\ \mathrm{d} \left( \frac{\partial \mathrm{vec} V}{\partial \theta} \right) \,\, \mathrm{vec} (V^{-1} - \varepsilon \varepsilon') &= \left[ \mathrm{M}^{11} \mathrm{d} \theta \,, \ldots, \mathrm{M}^{\mathrm{nn}} \mathrm{d} \theta \right] \mathrm{vec} (\Omega - \varepsilon \varepsilon') \\ &= \left[ \sum\limits_{\mathbf{i}, \mathbf{j}} (\omega_{\mathbf{i} \mathbf{j}} - \varepsilon_{\mathbf{i}} \varepsilon_{\mathbf{j}}) \mathrm{M}^{\mathbf{i} \mathbf{j}} \right] \,\, (\mathrm{d} \theta) \,\,. \end{split}$$

Further, since  $dV^{-1} = -V^{-1}(dV)V^{-1}$ , it follows that  $d \text{ vec } V^{-1} = -(V^{-1} \otimes V^{-1})\text{vec } dV = -(V^{-1} \otimes V^{-1}) \left(\frac{\partial \text{vec} V}{\partial \theta}\right)^{1} d\theta .$ 

Also, dvec 
$$\epsilon\epsilon' = \text{vec}(d\epsilon)\epsilon' + \text{vec}\epsilon(d\epsilon)'$$

$$= -\text{vec}X(d\beta)\epsilon' - \text{vec}\epsilon(d\beta)'X'$$

$$= -(\epsilon \otimes X) \text{vec}(d\beta) - (X \otimes \epsilon) \text{vec}(d\beta)' = -(\epsilon \otimes X + X \otimes \epsilon)(d\beta).$$

Collecting terms and inserting into (15) we find

$$\begin{split} \mathrm{d}^2\Lambda = -(\mathrm{d}\beta)'\mathrm{X}'\mathrm{VX}(\mathrm{d}\beta) \, + \, (\mathrm{d}\beta)'(\varepsilon' \otimes \mathrm{X}') & \left[\frac{\partial \mathrm{vec}V}{\partial \theta}\right]' \mathrm{d}\theta \\ + \, \frac{1}{2}(\mathrm{d}\theta)' & \left[\sum_{\mathbf{i},\mathbf{j}} (\omega_{\mathbf{i}\mathbf{j}} - \varepsilon_{\mathbf{i}}\varepsilon_{\mathbf{j}}) \mathrm{M}^{\mathbf{i}\mathbf{j}}\right] (\mathrm{d}\theta) \, - \, \frac{1}{2}(\mathrm{d}\theta)' & \left(\frac{\partial \mathrm{vec}V}{\partial \theta}\right) (\mathrm{V}^{-1} \otimes \mathrm{V}^{-1}) & \left(\frac{\partial \mathrm{vec}V}{\partial \theta}\right)' (\mathrm{d}\theta) \\ + \, \frac{1}{2}(\mathrm{d}\theta)' & \left(\frac{\partial \mathrm{vec}V}{\partial \theta}\right) (\varepsilon \otimes \mathrm{X} + \mathrm{X} \otimes \varepsilon) (\mathrm{d}\beta). \end{split}$$

We finally observe that, since dV is symmetric, it follows from (7) that

$$\varepsilon'(dV)X = (\text{vec } dV)'(X \otimes \varepsilon) = (\text{vec } dV)'(\varepsilon \otimes X).$$

This implies that

$$(d\theta)'\left[\frac{\partial \mathbf{vecV}}{\partial \theta}\right] (X \otimes \varepsilon) = (d\theta)'\left[\frac{\partial \mathbf{vecV}}{\partial \theta}\right] (\varepsilon \otimes X),$$

so that

$$d^{2}\Lambda = -(d\beta)'X'VX(d\beta) + 2(d\theta)'\left(\frac{\partial vecV}{\partial \theta}\right) (X \otimes \varepsilon)(d\beta)$$

$$+ \frac{1}{2}(d\theta)'\left[\sum_{i,j}(\omega_{ij} - \varepsilon_{i}\varepsilon_{j})M^{ij} - \left(\frac{\partial vecV}{\partial \theta}\right) (V^{-1} \otimes V^{-1})\left(\frac{\partial vecV}{\partial \theta}\right)'\right](d\theta). \quad (16)$$

This concludes the proof.

Of particular interest is the information matrix  $\Psi$ , defined as minus the expectation of the Hessian matrix.

#### Theorem 3

The information matrix of the loglikelihood function (11) is

$$\Psi = \begin{bmatrix} X'\Omega^{-1}X & 0 \\ 0 & \frac{1}{2}\Psi_{\theta} \end{bmatrix} , \qquad (17)$$

where  $\Psi_{\theta}$  is a symmetric (m,m) matrix with typical element

$$(\Psi_{\theta})_{ij} = tr\left(\frac{\partial \Omega^{-1}}{\partial \theta_{i}}\right) \Omega \left(\frac{\partial \Omega^{-1}}{\partial \theta_{j}}\right) \Omega$$
 (i,j=1...m). (18)

proof

Since  $E\varepsilon=0$  and  $E\varepsilon_{i}\varepsilon_{j}=\omega_{ij}$ , it follows that

$$\Psi = -\begin{bmatrix} EH_{11} & EH_{12}' \\ EH_{12} & EH_{22} \end{bmatrix} = \begin{bmatrix} X'\Omega^{-1}X & 0 \\ 0 & \frac{1}{2} \left(\frac{\partial \text{vecV}}{\partial \theta}\right) (V^{-1} \otimes V^{-1}) \left(\frac{\partial \text{vecV}}{\partial \theta}\right)' \end{bmatrix}.$$

Let  $\Psi_{\theta} = \left(\frac{\partial \text{vecV}}{\partial \theta}\right) (\text{V}^{-1} \otimes \text{V}^{-1}) \left(\frac{\partial \text{vecV}}{\partial \theta}\right)'$ , then  $\Psi_{\theta}$  is a symmetric (m,m) matrix whose ij-th element is

$$\left(\operatorname{vec} \frac{\partial V}{\partial \theta_{\mathbf{i}}}\right)' \left(V^{-1} \otimes V^{-1}\right) \left(\operatorname{vec} \frac{\partial V}{\partial \theta_{\mathbf{j}}}\right) = \operatorname{tr} \left(\frac{\partial V}{\partial \theta_{\mathbf{i}}}\right) V^{-1} \left(\frac{\partial V}{\partial \theta_{\mathbf{j}}}\right) V^{-1} ,$$

according to (6)

Sometimes the information matrix is defined as  $E\left(\frac{\partial \Lambda}{\partial \zeta}\right)^{\prime} \left(\frac{\partial \Lambda}{\partial \zeta}\right)^{\prime}$ , where  $\zeta' = (\beta' : \theta')$ . We shall see in lemma (5) that this leads to the same expressions.

Now we have to ensure that  $\Psi_{\theta}$  is a nonsingular matrix. We therefore need the following assumption:

ASSUMPTION 5: The m vectors  $\text{vec} \ \frac{\partial \Omega^{-1}}{\partial \theta_1} \ , \dots, \ \text{vec} \ \frac{\partial \Omega^{-1}}{\partial \theta_m} \ \text{are linearly independent.}$ 

#### lemma 1

Under the assumptions (1) - (5), the matrix  $\Psi$  as defined in (17) is positive definite.

#### Remark

Assumption five is also important for identification of the parameters. Suppose for example that  $\Omega = (\theta_1 + \theta_2)I$ , then  $\theta_1$  and  $\theta_2$  are unidentified. Such a parametrization is made impossible by assumption five.

#### 5. Finite properties of the two-step Aitken estimator and the ML estimator

In section three we defined the loglikelihood function

$$\Lambda = \gamma + \frac{1}{2} \log |\Omega^{-1}| - \frac{1}{2} \varepsilon' \Omega^{-1} \varepsilon , \qquad (19)$$

and we found that  $\Lambda$  is maximized when

(i) 
$$\beta = (X'\Omega^{-1}X)^{-1}X'\Omega^{-1}y$$

(ii)  $\operatorname{tr}\left(\frac{\partial\Omega^{-1}}{\partial\theta_{h}}\right)\Omega = e'\left(\frac{\partial\Omega^{-1}}{\partial\theta_{h}}\right)e$  (h=1...m).

Only in trivial cases, however, the system in (20) can be solved algebraically for the ML values of  $\beta$  and  $\theta$ . We therefore consider the following iterative procedure <sup>6</sup>)

- (i) Choose  $\theta = \theta_0 \in \Theta$  , the class of admissible values of  $\theta$ .
- (ii) Calculate  $\Omega_0^{-1} = \Omega^{-1}(\theta_0)$ ,

$$b_0 = (x' \Omega_0^{-1} x)^{-1} x' \Omega_0^{-1} y$$
,

This is by no means the only numerical method to find the roots of (20)

The Newton-Raphson iteration, for example, does the same job. It involves, however, inversion of the Hessian matrix at each step of the algorithm. On the other hand, it does not need a solution of the  $\theta$ -equation, as the procedure in

$$e_0 = y - Xb_0$$
.

(iii) Substitute  $e_0$  into the  $\theta$ -equation. This gives m (nonlinear) equations in m unknowns (the  $\theta$ 's). When it is possible to write the  $\theta$ -equation explicitly as  $\theta$  =  $\theta$ (e), we put  $\theta_1$  =  $\theta$ (e<sub>0</sub>). When an explicit solution of the  $\theta$ -equation does not exist, we may find more than one solution. In that case we select the solution with the highest likelihood. This is  $\theta_1$ .

(iv) Calculate 
$$\Omega_1^{-1} = \Omega^{-1}(\theta_1)$$
,
$$b_1 = (X'\Omega_1^{-1}X)^{-1}X'\Omega_1^{-1}Y$$
,

and so forth, until convergence.

Oberhofer and Kmenta (1974) prove that, under very general conditions (their assumption 6), the above procedure converges to a solution of the first-order maximizing conditions.

The uniqueness of the ML solution is contained in the following

#### lemma 2

Suppose that the estimators obtained for  $\beta$  and  $\theta$  are consistent at each step of the above iterative procedure. Then we have formed, upon convergence, a consistent root of the ML equations. This root is the unique ML estimator.

#### proof

See e.g. Cramer (1946) or Dhrymes (1970, Chapter three)

The consistency of the estimators of  $\beta$  and  $\theta$  is studied in the next section.

#### Definition 1

The two-step Aitken estimator  $b_1(\theta_0)$  is the estimator  $b_1$  defined by the above algorithm, based on the initial value  $\theta_0$ .

#### Definition 2

The <u>pure Aitken estimator</u>  $b^*$  is  $(X'\Omega^{-1}X)^{-1}X'\Omega^{-1}y$ , where  $\Omega$  (or  $\sigma^2\Omega$ ) is the true covariance matrix of the disturbances.

#### Lemma 3

The two-step Aitken estimator  $b_1(\theta_0)$  is distributed symmetrically around  $\beta$ ; it is unbiased if its mean exists.

#### proof

Since  $\epsilon$  is symmetrically distributed, it follows from a line of thought applied by Kakwani (1967) that it is sufficient to show that  $\Omega_1$  is an even function of  $\epsilon$ . Now, according to the algorithm,  $\theta_1$  is a solution of

$$\operatorname{tr}\left(\frac{\partial \Omega^{-1}}{\partial \theta_{h}}\right) \Omega = e_{0}^{\prime}\left(\frac{\partial \Omega^{-1}}{\partial \theta_{h}}\right) e_{0}$$
 (h=1...m),

where  $e_0 = y - Xb_0 = [I - X(X'\Omega_0^{-1}X)^{-1}X'\Omega_0^{-1}]y = [I - X(X'\Omega_0^{-1}X)^{-1}X'\Omega_0^{-1}]\epsilon$ .

If  $\varepsilon$  changes sign,  $e_0$  will change sign, but the expressions

$$e_0'\left(\frac{\partial\Omega^{-1}}{\partial\theta_h}\right)e_0$$

will not be affected. Thus  $\theta_1$  is an even function of  $\epsilon,$  which implies that  $\Omega_1$  is an even function of  $\epsilon.$ 

#### Lemma 4

In so far as iteration leads to the ML estimator  $\beta$ , it is unbiased, if its mean exists.

#### proof

In the proof of lemma (3) it was shown that  $\Omega_1$  is an even function of  $\varepsilon$ . This implies that  $e_1 = \left[ I - X(X'\Omega_1^{-1}X)^{-1}X'\Omega_1^{-1} \right] \varepsilon$  also is an even function of  $\varepsilon$ . But, since  $\Omega_2$  is an even function of  $e_1$ , it follows that  $\Omega_2$  is an even function of  $\varepsilon$ . Therefore  $b_2(\theta_0)$  is unbiased if its mean exists. It is now clear that iteration does not affect the unbiasedness of the estimator of  $\beta$ .

The existence of expectations is investigated in Swamy and Mehta (1969), Fuller and Battese (1973) and Mehta and Swamy (1976).

#### Lemma 5

The multivariate normal density of  $\epsilon$  (with parameters  $\beta$  and  $\theta$ ) is regular with respect to its first and second derivatives, i.e.

where  $\zeta = \begin{bmatrix} \beta \\ \theta \end{bmatrix}$ 

proof

From (13) we have

$$\partial \Lambda/\partial \beta = X'\Omega^{-1}\varepsilon$$
 and  $\partial \Lambda/\partial \theta = \frac{1}{2}\left(\frac{\partial \text{vec}\Omega^{-1}}{\partial \theta}\right) \text{vec}(\Omega-\varepsilon\varepsilon')$ .

Since Ee = 0 and Eee' =  $\Omega$ , it follows that E $\partial \Lambda/\partial \beta$  = 0 and E $\partial \Lambda/\partial \theta$  = 0, which proves (21).

In order to establish (22) we note that  $-E \ \partial^2 \Lambda/\partial \zeta \partial \zeta'$  is the information matrix  $\Psi$ . According to (17) and (18) we then have to prove the following equalities:

$$\begin{bmatrix} (i) & E(\partial \Lambda/\partial \beta)(\partial \Lambda/\partial \beta)' = X'\Omega^{-1}X \\ \\ (ii) & E(\partial \Lambda/\partial \beta)(\partial \Lambda/\partial \theta)' = 0 \\ \\ (iii) & E[(\partial \Lambda/\partial \theta)(\partial \Lambda/\partial \theta)']_{ij} = \frac{1}{2} tr \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \Omega \frac{\partial \Omega^{-1}}{\partial \theta_{j}} \Omega \text{ (i,j=1...m)}$$

Now,

 $E(\partial \Lambda/\partial \beta)(\partial \Lambda/\partial \beta)' = E X'\Omega^{-1} \epsilon \epsilon' \Omega^{-1} X = X'\Omega^{-1} \Omega \Omega^{-1} X = X'\Omega^{-1} X.$  This proves (i). Further,

$$E(\partial \Lambda/\partial \beta)(\partial \Lambda/\partial \theta)' = \frac{1}{2}E X'\Omega^{-1}\epsilon \left[ \text{vec}(\Omega - \epsilon\epsilon') \right]' \left( \frac{\partial \text{vec}\Omega^{-1}}{\partial \theta} \right]'$$
$$= \frac{1}{2} X'\Omega^{-1} \left[ E \epsilon \left\{ \text{vec}(\Omega - \epsilon\epsilon') \right\}' \right] \left( \frac{\partial \text{vec}\Omega^{-1}}{\partial \theta} \right)'.$$

Consider the (n,n<sup>2</sup>)matrix

$$\varepsilon[\text{vec}(\Omega-\varepsilon\varepsilon')]'$$
,

with typical element  $\varepsilon_{i}[\omega_{jk} - \varepsilon_{j}\varepsilon_{k}]$ . Since  $E\varepsilon_{i}\omega_{jk} = 0$  and  $E\varepsilon_{i}\varepsilon_{j}\varepsilon_{k} = 0$  for all i,j,k, it follows that

 $\operatorname{E\varepsilon}[\operatorname{vec}(\Omega - \varepsilon \varepsilon')]! = 0,$ 

which proves (ii).

Finally,

$$\begin{split} (\partial \Lambda/\partial \theta)(\partial \Lambda/\partial \theta)! &= \frac{1}{4} \left[ \frac{\partial \text{vec}\Omega^{-1}}{\partial \theta} \right] \text{vec}(\Omega - \epsilon \epsilon^{!}) \left[ \text{vec}(\Omega - \epsilon \epsilon^{!}) \right]! \left( \frac{\partial \text{vec}\Omega^{-1}}{\partial \theta} \right)^{!} \\ &= \frac{1}{4} \left[ \text{vec} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right]! \left[ \text{vec}(\Omega - \epsilon \epsilon^{!}) \left[ \text{vec}(\Omega - \epsilon \epsilon^{!}) \right]! \left( \text{vec} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \\ &= \frac{1}{4} \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \left( \Omega - \epsilon \epsilon^{!}) \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \\ &= \frac{1}{4} \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \left( \Omega - \epsilon \epsilon^{!}) \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \\ &= \frac{1}{4} \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \\ &= \frac{1}{4} \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \\ &= \frac{1}{4} \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \\ &= \frac{1}{4} \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \\ &= \frac{1}{4} \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \\ &= \frac{1}{4} \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \\ &= \frac{1}{4} \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right]! \right] \\ &= \frac{1}{4} \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \right] \\ &= \frac{1}{4} \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \\ &= \frac{1}{4} \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right] \right] \\ &= \frac{1}{4} \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right] \right] \\ &= \frac{1}{4} \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right)! \right] \\ \\ &= \frac{1}{4} \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right] \left[ \text{tr} \left( \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \right] \left[ \text{tr} \left( \frac{$$

Now,

$$E\epsilon' \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \epsilon = E \text{ tr } \epsilon' \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \epsilon = E \text{ tr } \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \epsilon \epsilon'$$

$$= \text{ tr } E \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \epsilon \epsilon' = \text{ tr } \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \Omega ,$$

so that the above expression can be written as

$$4\left[\left(\frac{\partial \Lambda}{\partial \theta}\right)\left(\frac{\partial \Lambda}{\partial \theta}\right)'\right]_{ij} = \left(\varepsilon' \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \varepsilon - E\varepsilon' \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \varepsilon\right)\left(\varepsilon' \frac{\partial \Omega^{-1}}{\partial \theta_{j}} \varepsilon - E\varepsilon' \frac{\partial \Omega^{-1}}{\partial \theta_{j}} \varepsilon\right).$$

Taking expectations we find

$$4E \left[ (\partial \Lambda/\partial \theta)(\partial \Lambda/\partial \theta)' \right]_{ij} = cov \left( \varepsilon' \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \varepsilon, \varepsilon' \frac{\partial \Omega^{-1}}{\partial \theta_{j}} \varepsilon \right)$$
$$= 2 \operatorname{tr} \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \Omega \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \Omega.$$

The last equality follows from Magnus and Neudecker (1977, p.16). This concludes the proof.

### 6. Asymptotic properties of the two-step Aitken estimator and the ML estimator

The asymptotic properties of estimators are almost without exception based on random sampling, that is on the statistical independence of the  $y_i$  (or  $\varepsilon_i$ ). In that case the central limit theorems apply. Our problem, however, consists in estimating  $\beta$  from a single (vector) observation on y.

A related complication is that  $\Omega$  increases in size when n increases. We shall need the following assumptions.

ASSUMPTION 6: The elements of  $Z_h = \frac{\partial \Omega^{-1}}{\partial \theta_h}$  (h=1...m) are continuous functions of  $\theta$  in an open sphere S  $\theta$  of  $\theta_0$ , the true value of the parameter vector  $\theta$ .

ASSUMPTION 7:  $\lim_{n\to\infty}\frac{1}{n}\,X'\Omega^{-1}X$  exists as a positive definite matrix of fixed constants for all  $\theta$  in S.

ASSUMPTION 8:  $\lim_{n\to\infty}\frac{1}{n}$  X'Z<sub>h</sub>X exists as a matrix whose elements are continous functions of  $\theta$  (h=1...m).

These assumptions enable us to formulate the following theorem due to Fuller and Battese (1973).

#### Theorem 4

Suppose there exists an estimator  $\tilde{\theta}$  for  $\theta_0$  such that  $\Omega^{-1}(\tilde{\theta})$  exists for all n, and  $\tilde{\theta} = \theta_0 + O(n^{-\delta})$ ,  $\delta > 0$ , then the assumptions (2) - (8) imply that

$$\beta_{n} - b_{n}^{*} = O(n^{-\frac{1}{2} - \delta}), \text{ where}$$

$$\tilde{\beta}_{n} = (X'\Omega^{-1}(\tilde{\theta})X)^{-1}X'\Omega^{-1}(\tilde{\theta})y$$
,

#### proof

See Fuller and Battese (1973, p. 629)

#### Corollary

Under the same assumptions as in theorem 4 we have

plim 
$$\beta_n = \text{plim } b_n^*$$
, and

 $\beta_n^*$  has the same asymptotic distribution as  $b_n^*$ ,

that is

plim 
$$\beta_n = \beta$$
, and

$$\sqrt{n}(\beta_n^--\beta)$$
 has asymptotic distribution N[0,  $\lim_{n\to\infty} n(X^*\Omega^{-1}X)^{-1}$ ].

We now turn to the ML estimators  $\beta$  and  $\theta$ . In the standard case of random sampling the value of the ML method lies in the fact that it generates estimators with desirable asymptotic properties. Let  $\zeta$  be such a ML estimator. Then  $\tau^{7}$ , under very general conditions,  $\tau^{7}$  is consistent, asymptotically unbiased and asymptotically efficient. Further  $\sqrt{n}(\zeta-\zeta)$  has asymptotic distribution N(0,  $\lim_{n\to\infty} n^{-1}$ ), where  $\Psi$  is the information matrix.

To deal with the more difficult non-standard case we need the following assumptions:

ASSUMPTION 9: Every element of  $\frac{1}{n} \times \Omega^{-1} \times \Omega$  converges as  $n \to \infty$  to a finite function of  $\theta$ , uniformly for  $\theta$  in any compact set.

ASSUMPTION 10: Every diagonal element of  $\frac{1}{n^2} \times \frac{\partial \Omega^{-1}}{\partial \theta_i} \Omega \xrightarrow{\partial \Omega^{-1}} X$  converges as  $n \to \infty$  to zero, uniformly for  $\theta$  in any compact set (i=1...m).

ASSUMPTION 11:  $\frac{1}{n}$  tr  $\frac{\partial \Omega^{-1}}{\partial \theta_{i}} \Omega \frac{\partial \Omega^{-1}}{\partial \theta_{j}} \Omega$  converges as  $n \to \infty$  to a finite function of  $\theta$ , uniformly for  $\theta$  in any compact set (i,j=1...m).

ASSUMPTION 12:  $\frac{1}{n^2}$  tr  $(\frac{\partial^2 \Omega^{-1}}{\partial \theta_i \partial \theta_j} \Omega)^2$  converges as  $n \to \infty$  to zero, uniformly for  $\theta$  in any compact set (i,j=1...m).

<sup>7)</sup> See Kendall and Stuart (1967), Chapter 18.

# Theorem 5 8

The ML estimates  $\hat{\beta}$  and  $\hat{\theta}$  from the regression model (8) under the assumptions (1) - (5) and (9) - (12) are weakly consistent, asymptotically normally distributed, and asymptotically efficient in the maximum probability sense of Weiss and Wolfowitz (1967).

#### proof

It suffices to prove that the assumptions (2.1) and (2.2) of Weiss (1973) reduce to our assumptions (9) - (12). This is greatly facilitated by applying three theorems in Vickers (1977, section 1.4).

Let H = (h ij) be the Hessian matrix from theorem 2 and  $\Psi$  = ( $\psi$  ij) the information matrix from theorem 3. The implication of Vickers' theorems is that  $\hat{\beta}$  and  $\hat{\theta}$  are weakly consistent, asymptotically normally distributed and assymptotically efficient in the maximum probability sense, if

- (a)  $\frac{1}{n} \psi_{ij}$  converges as  $n \to \infty$  to a finite function of  $\beta$  and  $\theta$ , uniformly for values  $\beta$  and  $\theta$  in any compact set (i,j=1...k+m),
- (b)  $\frac{1}{n^2}$  var(h<sub>ij</sub>) converges as n→∞ to zero, uniformly for values  $\beta$  and  $\theta$  in any compact set (i,j=1...k+m).

We shall now show that the assumption (a) and (b) reduce to (9)-(12). Partition

$$x = (x_1 \dots x_k),$$

then

$$\frac{\partial^{2} \Lambda}{\partial \beta_{i} \partial \beta_{j}} = -x_{i}^{!} \Omega^{-1} x_{j} \qquad (i,j=1...k),$$

$$\frac{\partial^{2} \Lambda}{\partial \theta_{i} \partial \beta_{j}} = x_{j}^{!} \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \epsilon \qquad (i=1...m,j=1...k),$$

$$\frac{\partial^{2} \Lambda}{\partial \theta_{i} \partial \theta_{j}} = -\frac{1}{2} \left[ \operatorname{tr} \frac{\partial \Omega^{-1}}{\partial \theta_{i}} \Omega \frac{\partial \Omega^{-1}}{\partial \theta_{j}} \Omega + \epsilon' \frac{\partial^{2} \Omega^{-1}}{\partial \theta_{i} \partial \theta_{j}} \epsilon - \operatorname{tr} \frac{\partial^{2} \Omega^{-1}}{\partial \theta_{i} \partial \theta_{j}} \Omega \right] \qquad (i,j=1...m)$$

I am grateful to professor Lionel Weiss and Dr. Kathleen Vickers for calling my attention to their work. Theorem five is a direct application of Dr. Vickers' Ph.D. thesis.

Thus,

$$\begin{split} & \mathbb{E}\left[-\frac{\partial^{2} \Lambda}{\partial \beta_{1} \partial \beta_{j}}\right] = \mathbf{x}_{1}^{!} \Omega^{-1} \mathbf{x}_{j} , \\ & \mathbf{var}\left[-\frac{\partial^{2} \Lambda}{\partial \beta_{1} \partial \beta_{j}}\right] = 0 , \\ & \mathbb{E}\left[-\frac{\partial^{2} \Lambda}{\partial \theta_{1} \partial \beta_{j}}\right] = 0 , \\ & \mathbb{E}\left[-\frac{\partial^{2} \Lambda}{\partial \theta_{1} \partial \beta_{j}}\right] = \mathbf{x}_{j}^{!} \frac{\partial \Omega^{-1}}{\partial \theta_{1}} \Omega \frac{\partial \Omega^{-1}}{\partial \theta_{1}} \mathbf{x}_{j} , \\ & \mathbb{E}\left[-\frac{\partial^{2} \Lambda}{\partial \theta_{1} \partial \theta_{j}}\right] = \frac{1}{2} \operatorname{tr} \frac{\partial \Omega^{-1}}{\partial \theta_{1}} \Omega \frac{\partial \Omega^{-1}}{\partial \theta_{j}} \Omega , \\ & \mathbb{E}\left[-\frac{\partial^{2} \Lambda}{\partial \theta_{1} \partial \theta_{j}}\right] = \frac{1}{2} \operatorname{tr} \frac{\partial \Omega^{-1}}{\partial \theta_{1}} \Omega \frac{\partial \Omega^{-1}}{\partial \theta_{j}} \Omega , \\ & \mathbb{E}\left[-\frac{\partial^{2} \Lambda}{\partial \theta_{1} \partial \theta_{j}}\right] = \frac{1}{4} \operatorname{var}\left[\mathbb{E}^{!} \frac{\partial^{2} \Omega^{-1}}{\partial \theta_{1} \partial \theta_{j}} \mathbb{E}\right] = \frac{1}{2} \operatorname{tr} \left(\frac{\partial^{2} \Omega^{-1}}{\partial \theta_{1} \partial \theta_{j}} \Omega\right)^{2}. \end{split}$$

It is now clear that (a) reduces to the assumptions (9) and (11), and that (8) reduces to (10) and (12). This concludes the proof.

#### 7. A general case

We shall apply the above theory to the autocorrelated errors model and to Zellner-type regressions 9, but before doing so we first study a more general case which will simplify the discussion in the next two sections.

Consider a covariance matrix of the following form

$$\Omega = \begin{bmatrix} \sigma_{11}^{Q} Q_{1}^{\Gamma Q_{1}^{\prime}} & \cdots & \sigma_{1p}^{Q} Q_{1}^{\Gamma Q_{p}^{\prime}} \\ \sigma_{p1}^{Q} Q_{p}^{\Gamma Q_{1}^{\prime}} & \cdots & \sigma_{pp}^{Q} Q_{p}^{\Gamma Q_{p}^{\prime}} \end{bmatrix} = Q(\Sigma \otimes \Gamma)Q^{\prime} , \qquad (23)$$

Applications to the heteroskedastic model and to error component analysis are studied in Magnus (1977 a,b).

where  $\Sigma$  and  $\Gamma$  are symmetric positive definite matrices of order p and T respectively, p  $\leq$  T<sup>10</sup>, p fixed. The number of observations is n=pT. Further,

where the  $Q_1$  (i=1...p) are nonsingular matrices of order T. The covariance matrix (23) is clearly a generalization of Zellner's case of seemingly unrelated regressions. It is also an extension of  $\Omega$  itself, as can be seen by putting p=1. The matrix then reduces to

$$Ω = σ2QΓQ'$$
,

where  $\Gamma$  is positive definite and Q is nonsingular.

In the next section, where we study the autocorrelated errors model, we shall work with  $\Omega=QQ^{\dagger}$ , which simplifies matters greatly.

We suppose that  $\Sigma$  is completely unknown, thus containing  $\frac{1}{2}p(p+1)$  parameters,  $Q=Q(\zeta)$ , and  $\Gamma=\Gamma(\xi)$ , where  $\zeta$  and  $\xi$  are parameter vectors containing q and r components respectively.

Thus  $\theta$  consists of the elements of  $\zeta$  and  $\xi$  and of the  $\frac{1}{2}p(p+1)$  distinct elements  $\sigma_{hk}$  of  $\Sigma$ .

$$\begin{aligned} &\theta' = \left[ \zeta', \xi', \mathring{\sigma}' \right] \quad \text{, where} \\ &\zeta' = \left[ \zeta_1 \dots \zeta_q \right] \quad \text{,} \\ &\xi' = \left[ \xi_1 \dots \xi_r \right] \quad \text{,} \\ &\mathring{\sigma}' = \left[ \sigma_{11}, \sigma_{12}, \dots, \sigma_{1p}, \sigma_{22}, \dots, \sigma_{2p}, \dots, \sigma_{pp} \right] \text{.} \end{aligned}$$

<sup>10)</sup> This is necessary to ensure the nonsingularity of the estimator of  $\Sigma$ .

To derive the  $\theta$ -conditions we proceed as follows:

$$\Omega^{-1} = (Q^{-1})'(\Sigma^{-1} \otimes \Gamma^{-1})Q^{-1}$$

$$\begin{split} \mathrm{d}\Omega^{-1} &= (\mathrm{d}Q^{-1})^{*}(\Sigma^{-1} \otimes \Gamma^{-1})Q^{-1} + (Q^{-1})^{*}(\Sigma^{-1} \otimes \Gamma^{-1})(\mathrm{d}Q^{-1}) \\ &+ (Q^{-1})^{*}\left[(\mathrm{d}\Sigma^{-1}) \otimes \Gamma^{-1}\right]Q^{-1} + (Q^{-1})^{*}\left[\Sigma^{-1} \otimes (\mathrm{d}\Gamma^{-1})\right]Q^{-1} \end{split}$$

From this it follows that

(i) 
$$\frac{\partial \Omega^{-1}}{\partial \zeta_{i}} = \left(\frac{\partial Q^{-1}}{\partial \zeta_{i}}\right)'(\Sigma^{-1} \otimes \Gamma^{-1})Q^{-1} + (Q^{-1})'(\Sigma^{-1} \otimes \Gamma^{-1})\frac{\partial Q^{-1}}{\partial \zeta_{i}}$$
(i=1...q)

(ii) 
$$\frac{\partial \Omega^{-1}}{\partial \xi_{j}} = (Q^{-1})! \left( \Sigma^{-1} \otimes \frac{\partial \Gamma^{-1}}{\partial \xi_{j}} \right) Q^{-1}$$
 (j=1...r)

$$(iii) \ \frac{\partial \Omega^{-1}}{\partial \sigma_{\mathrm{hk}}} = -(Q^{-1})! \left[ (\Sigma^{-1} Y^{\mathrm{hk}} \Sigma^{-1}) \otimes \Gamma^{-1} \right] Q^{-1} \quad (1 \leqslant h \leqslant k \leqslant p),$$

where  $Y^{hk}$  is a square matrix of order p with zeros everywhere except in the hk-th and kh-th position where it has unity
and (iii) follows from the fact that

$$d\Sigma^{-1} = -\Sigma^{-1}(d\Sigma)\Sigma^{-1}$$

so that

$$\frac{\partial \Sigma^{-1}}{\partial \sigma_{hk}} = -\Sigma^{-1} Y^{hk} \Sigma^{-1}.$$

Now define the following matrices:

(i) 
$$G_{\zeta}^{i} = \frac{\partial \Omega^{-1}}{\partial \zeta_{i}} \Omega = \left(\frac{\partial Q^{-1}}{\partial \zeta_{i}}\right)' Q' + (Q^{-1})' (\Sigma^{-1} \otimes \Gamma^{-1}) \frac{\partial Q^{-1}}{\partial \zeta_{i}} Q(\Sigma \otimes \Gamma) Q' \text{ (i=1...q)}$$

(ii) 
$$G_{\xi}^{j} = \frac{\partial \Omega^{-1}}{\partial \xi_{j}} \Omega = (Q^{-1})! \left[ I \otimes \frac{\partial \Gamma^{-1}}{\partial \xi_{j}} \Gamma \right] Q!$$
 (j=1...r)

(iii) 
$$G_{\sigma}^{hk} = \frac{\partial \Omega^{-1}}{\partial \sigma_{hk}} \Omega = -(Q^{-1})'(\Sigma^{-1}Y^{hk} \otimes I)Q'$$
 (1  $\leq h \leq k \leq p$ ).

The traces of these matrices are:

(i) 
$$\operatorname{tr} G_{\zeta}^{i} = 2 \operatorname{tr} \frac{\partial Q^{-1}}{\partial \zeta_{i}} Q$$
 (i=1...q)

(ii) 
$$\operatorname{tr} G_{\xi}^{j} = p \operatorname{tr} \frac{\partial \Gamma^{-1}}{\partial \xi_{j}} \Gamma$$
 (j=1...r)

(iii) tr 
$$G_{\sigma}^{hk}$$
 = -T tr( $\Sigma^{-1}Y^{hk}$ ) (1  $\leq$  h  $\leq$  k  $\leq$  p).

Let 
$$e' = [e'_1, e'_2, \dots, e'_p]$$
,  $z_h = Q_h^{-1} e_h$ ,  $z_{hi} = \frac{\partial Q_h^{-1}}{\partial \zeta_i} e_h$  (h=1...p;i=1...q),

$$Z = [z_1, z_2, \dots, z_p]$$
 ,  $\tilde{Z}_i = [\tilde{z}_{1i}, \tilde{z}_{2i}, \dots, \tilde{z}_{pi}]$  (i=1...q).

Then  $Q^{-1}e = \text{vec } Z \text{ and } \frac{\partial Q^{-1}}{\partial \zeta_i} e = \text{vec } Z_i$ ,

so that

(i) 
$$e'\frac{\partial\Omega^{-1}}{\partial\zeta_{i}} = 2e'\left(\frac{\partial Q^{-1}}{\partial\zeta_{i}}\right)'(\Sigma^{-1} \otimes \Gamma^{-1})Q^{-1}e = 2(\text{vec } \widetilde{Z}_{i})'(\Sigma^{-1} \otimes \Gamma^{-1})\text{vec } Z$$

$$= 2\text{tr}\Gamma^{-1}Z\Sigma^{-1}\widetilde{Z}_{i}' \qquad (i=1...q)$$

(ii) 
$$e^{i\frac{\partial\Omega^{-1}}{\partial\xi_{j}}}e = (\text{vec Z})^{i}(\Sigma^{-1} \otimes \frac{\partial\Gamma^{-1}}{\partial\xi_{j}})\text{vec Z} = \text{tr}\frac{\partial\Gamma^{-1}}{\partial\xi_{j}}\text{Z}\Sigma^{-1}\text{Z}^{i}$$
 (j=1...r)

(iii) 
$$e^{i\frac{\partial\Omega^{-1}}{\partial\sigma_{hk}}} = -(\text{vec }Z)^{i} \left[ (\Sigma^{-1}Y^{hk}\Sigma^{-1}) \otimes \Gamma^{-1} \right] \text{ vec } Z = -\text{tr } \Sigma^{-1}Z^{i}\Gamma^{-1}Z\Sigma^{-1}Y^{hik}$$
(1 < h < k < p).

The  $\theta$ -conditions (10) are in the present case:

(i) 
$$\operatorname{tr} \frac{\partial Q^{-1}}{\partial \zeta_{i}} Q = \operatorname{tr} \Gamma^{-1} Z \Sigma^{-1} Z_{i}^{!}$$
 (i=1...q)  
(ii)  $\operatorname{p} \operatorname{tr} \frac{\partial \Gamma^{-1}}{\partial \xi_{j}} \Gamma = \operatorname{tr} \frac{\partial \Gamma^{-1}}{\partial \xi_{j}} Z \Sigma^{-1} Z^{!}$  (j=1...r)  
(iii)  $\Sigma = \frac{1}{T} Z^{!} \Gamma^{-1} Z$ ,

where (i) and (ii) are obvious and (iii) follows from

$$-T \operatorname{tr}^{-1} Y^{hk} = -\operatorname{tr}^{-1} Z' \Gamma^{-1} Z \Sigma^{-1} Y^{hk} \qquad (1 \le h \le k \le p)$$

or

$$tr(T\Sigma^{-1} - \Sigma^{-1}Z^{\dagger}\Gamma^{-1}Z\Sigma^{-1})Y^{hk} = 0$$
 (1 < h < k < p).

This is equivalent with

$$T\Sigma^{-1} = \Sigma^{-1}Z'\Gamma^{-1}Z\Sigma^{-1}$$

which in turn is equivalent with (iii).

Now define 
$$K_i = \frac{\partial Q^{-1}}{\partial \zeta_i} Q$$
 (i=1...q) and  $C_j = \frac{\partial \Gamma^{-1}}{\partial \xi_j} \Gamma$  (j=1...r), and let 
$$g(h,k) = k + (h-1)(p-\frac{1}{2}h) \qquad (1 \le h \le k \le p),$$

then

$$\theta_{g(h,k)+q+r} = \sigma_{hk}$$
,

and the symmetric matrix  $\boldsymbol{\Psi}_{\boldsymbol{\theta}}$  from the information matrix (17) takes the form

$$\Psi_{\theta} = r \begin{bmatrix} \Psi_{\zeta\zeta} & \Psi_{\zeta\xi} & \Psi_{\zeta\sigma} \\ \vdots & \Psi_{\xi\xi} & \Psi_{\xi\sigma} \\ \vdots & \vdots & \Psi_{\sigma\sigma} \end{bmatrix}$$

where 11)

(i) 
$$\begin{bmatrix} (\Psi_{\zeta\zeta})_{ij} &= \operatorname{trG}_{\zeta}^{i}G_{\zeta}^{j} &= 2\operatorname{trK}_{i}K_{j} + 2\operatorname{trK}_{i}^{i}(\Sigma^{-1} \otimes \Gamma^{-1})K_{j}(\Sigma \otimes \Gamma) & (i,j=1...q) \\ (ii) & (\Psi_{\zeta\xi})_{ij} &= \operatorname{trG}_{\zeta}^{i}G_{\xi}^{j} &= 2\operatorname{trK}_{i}^{i}(I \otimes C_{j}) & (i=1...q,j=1...r) \\ (iii) & (\Psi_{\xi\xi})_{ij} &= \operatorname{trG}_{\xi}^{i}G_{\xi}^{j} &= \operatorname{ptrC}_{i}C_{j} & (i,j=1...r) \\ (iv) & (\Psi_{\zeta\sigma})_{i,g(h,k)} &= \operatorname{trG}_{\xi}^{i}G_{\sigma}^{hk} &= -2\operatorname{trK}_{i}^{i}(\Sigma^{-1}Y^{hk} \otimes I) & (i=1...q,g(h,k)=1...\frac{1}{2}p(p+1)) \\ (v) & (\Psi_{\xi\sigma})_{j,g(h,k)} &= \operatorname{trG}_{\xi}^{j}G_{\sigma}^{hk} &= -(\operatorname{tr}\Sigma^{-1}Y^{hk})\operatorname{trC}_{j} &= \begin{bmatrix} -2\sigma^{hk}\operatorname{trC}_{j} & \text{if } h\neq k \\ -\sigma^{hh}\operatorname{trC}_{j} & \text{if } h= k \end{bmatrix}$$

$$(26) & (j=1...r,g(h,k)=1...\frac{1}{2}p(p+1)) \\ (vi) & (\Psi_{\sigma\sigma})_{g(i,j),g(h,k)} &= \operatorname{trG}_{\sigma}^{ij}G_{\sigma}^{hk} &= \operatorname{Ttr}(\Sigma^{-1}Y^{ij})(\Sigma^{-1}Y^{hk}) \\ &= \begin{bmatrix} 2T(\sigma^{ih}\sigma^{jk} + \sigma^{ik}\sigma^{jh}) & \text{if } i\neq j \text{ and } h\neq k \\ 2T(\sigma^{ih}\sigma^{jh}) & \text{if } i\neq j \text{ and } h\neq k \\ 2T(\sigma^{ih}\sigma^{jh}) & \text{if } i\neq j \text{ and } h\neq k \end{bmatrix}$$

$$2T(\sigma^{ih}\sigma^{jh}) &= \operatorname{trG}_{\sigma}^{ij}G_{\sigma}^{hk} &= \operatorname{Ttr}(\Sigma^{-1}Y^{ij})(\Sigma^{-1}Y^{hk}) \\ = 2T(\sigma^{ih}\sigma^{jh}) &= \operatorname{TrG}_{\sigma}^{ij}G_{\sigma}^{hk} &= \operatorname{TtG}_{\sigma}^{ij}G_{\sigma}^{hk} &= \operatorname{TtG}_{\sigma}^{ij}G_{\sigma$$

 $(g(i,j),g(h,k) = 1...\frac{1}{2}p(p+1))$ 

<sup>11)</sup>  $\sigma^{hk}$  denotes the typical element of  $\Sigma^{-1}$ .

Finally, we give the expressions for the case p=1:

$$\Omega = \sigma^2 Q \Gamma Q' \qquad , \qquad (27)$$

where  $\Gamma=\Gamma(\xi)$  is positive definite and  $Q=Q(\zeta)$  is nonsingular, both of order n.

$$\theta' = \left[\zeta', \xi', \sigma^2\right]$$

The  $\theta$ -conditions are

$$\begin{bmatrix}
(i) & \sigma^{2} \text{tr} K_{i} = e^{i} \left( \frac{\partial Q^{-1}}{\partial \zeta_{i}} \right)^{i} \Gamma^{-1} Q^{-1} e & \text{(i=1...q)} \\
(ii) & \sigma^{2} \text{tr} C_{j} = e^{i} (Q^{-1})^{i} \frac{\partial \Gamma^{-1}}{\partial \zeta_{j}} Q^{-1} e & \text{(j=1...r)} \\
(iii) & \sigma^{2} = \frac{1}{n} e^{i} (Q^{-1})^{i} Q^{-1} e & \text{,}
\end{bmatrix}$$
(28)

and

$$\psi_{\theta} = \mathbf{r} \begin{bmatrix} \Psi_{\zeta\zeta} & \Psi_{\zeta\xi} & \Psi_{\zeta\sigma} \\ \cdot & \Psi_{\xi\xi} & \Psi_{\xi\sigma} \\ \cdot & \cdot & \Psi_{\sigma\sigma} \end{bmatrix} , \qquad (29)$$

where

Let 
$$y=X\beta + \varepsilon$$
,  $\varepsilon_t=\rho\varepsilon_{t-1}+\zeta_t$ ,  $E\zeta=0$ ,  $E\zeta\zeta'=\sigma^2I_n$ ,  $|\rho|<1$ . (31)

These conditions do not specify the standard first-order autocorrelated errors model completely; one more assumption is needed as to the initial value of the disturbances.

For the moment we shall only assume that

$$\varepsilon_1 - \rho \varepsilon_0 = \phi \varepsilon_1$$
,

where  $\phi$  may depend on  $\rho$ ;  $\phi > 0$ .

This implies that  $\zeta_1$  = $\phi\epsilon_1$  , so that we can write

$$\zeta = A\epsilon$$
 , where  $A = \begin{bmatrix} \phi \\ -\rho & 1 \\ & \ddots & \\ & -\rho & 1 \end{bmatrix}$  .

Now 
$$\sigma^2 I = E\zeta\zeta' = EA\varepsilon\varepsilon'A' = A(E\varepsilon\varepsilon')A'$$
, so 
$$\Omega = E\varepsilon\varepsilon' = \sigma^2 A^{-1}(A^{-1})'$$
.

According to (28) the  $\theta$ -conditions are

$$\begin{bmatrix}
(i) & \sigma^2 \text{tr} K = e' \left( \frac{\partial A}{\partial \rho} \right)' \text{Ae} \\
(ii) & \sigma^2 = \frac{1}{n} e' \text{A'Ae}
\end{bmatrix} (32)$$

where  $K = \frac{\partial A}{\partial \rho} A^{-1}$ . Let  $\phi' = \partial \phi/\partial \rho$ ,

then 
$$\frac{\partial A}{\partial \rho} = \begin{bmatrix} \phi' \\ -1 & 0 \\ & \ddots \\ & -1 & 0 \end{bmatrix}$$
.

Since

$$A^{-1} = \begin{bmatrix} \phi^{-1}_{-1} & 0 & \cdots & 0 \\ \phi^{-1}_{\rho} & 1 & & & 0 \\ \vdots & \rho & \ddots & & \\ \phi^{-1}_{\rho} & 1 & n-2 & \cdots & \rho & 1 \end{bmatrix}$$

We find that

$$K = -\begin{bmatrix} -\phi'\phi^{-1} & 0 & \cdots & 0 \\ -\phi'^{-1} & 0 & \cdots & 0 \\ \phi^{-1} & 0 & 0 \\ \phi^{-1}\rho & 1 & \cdots & 0 \\ \vdots & \ddots & \ddots & \vdots \\ \phi^{-1}\rho^{n-2} & \rho^{n-3} & \cdots & \rho & 1 & 0 \end{bmatrix}$$

Clearly, trK = 
$$\phi'\phi^{-1}$$
.  
Further  $e'A'Ae = \sum_{i=2}^{\Sigma} (e_i - \rho e_{i-1})^2 + \phi^2 e_1^2 = \sum_{i=1}^{n} (e_i - \rho e_{i-1})^2$ ,

where 
$$e_0 = \frac{1-\phi}{\rho} e_1$$

$$e'\left(\frac{\partial A}{\partial \rho}\right)'Ae = \phi\phi'e_1^2 + \frac{n-1}{\rho \Sigma e_1^2} - \frac{n-1}{\Sigma e_1^2 e_{1+1}}$$

The  $\theta$ -conditions (32) boil down to

$$\begin{bmatrix}
(i) & \hat{\sigma}^2 \phi' \phi^{-1} = \phi \phi' e_1^2 + \hat{\rho}^{n-1} \sum_{i=1}^{n} e_i^2 - \sum_{i=1}^{n-1} e_{i+1}^2 \\
(ii) & \hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^{n} (e_i - \hat{\rho} e_{i-1}^2)^2
\end{bmatrix}$$

In order to compute the information matrix we need

$$trK^2 = (\phi'\phi^{-1})^2,$$

trK'K = the sum of the squared elements of K

$$= (\phi'\phi^{-1})^{2} + \phi^{-2} \sum_{i=0}^{n-2} \rho^{2i} + \sum_{k=0}^{n-3} \sum_{i=0}^{k} \rho^{2i}$$

$$= (\phi^{\dagger} \phi^{-1})^2 + \phi^{-2} \frac{1-\rho^{2(n-1)}}{1-\rho^{2}} + \sum_{k=0}^{n-3} \frac{1-\rho^{2(k+1)}}{1-\rho^{2}}$$

$$= (\phi'\phi^{-1})^2 + \frac{1}{1-\rho^2} \left[ \phi^{-2} (1-\rho^{2(n-1)}) + (n-2) - \frac{\rho^2}{1-\rho^2} (1-\rho^{2(n-2)}) \right]^{\frac{1}{2}}$$

$$= (\phi'\phi^{-1})^2 + \frac{1}{1-\rho^2} \left[ n - (1-\phi^{-2})(1-\rho^{2(n-1)}) - \frac{1}{1-\rho^2} (1-\rho^{2n}) \right].$$

According to (29) and (30) the matrix  $\Psi_{\theta}$  is

$$\Psi_{\theta} = \begin{bmatrix} \psi_{\rho\rho} & \psi_{\rho\sigma} \\ \vdots & \psi_{\sigma\sigma} \end{bmatrix} , \qquad (33)$$

where

$$\begin{bmatrix} \psi_{\rho\rho} = 2 \text{tr} K^2 + 2 \text{tr} K'K = 4(\phi'\phi^{-1})^2 + \frac{2}{1-\rho^2} \left[ n - (1-\phi^{-2})(1-\rho^{2(n-1)}) - \frac{1}{1-\rho^2}(1-\rho^{2n}) \right]$$

$$\psi_{\rho\sigma} = 2\sigma^{-2} \text{tr} K = 2\sigma^{-2}\phi'\phi^{-1}$$

$$\psi_{\sigma\sigma} = n\sigma^{-4} .$$

Two cases are of particular interest:

## Case (i): iterative Cochrane-Orcutt

When  $\phi=1$ , the ML conditions are simply

$$\hat{\rho} = \frac{\sum_{i=1}^{n-1} e_{i}^{2}}{\sum_{i=1}^{n-1} e_{i}^{2}}$$

$$\hat{\beta} = (X'\hat{A}'\hat{A}X)^{-1}X'\hat{A}'\hat{A}y$$

$$\hat{\sigma}^{2} = \frac{1}{n} \sum_{i=1}^{n} (e_{i}^{-\hat{\rho}}e_{i-1}^{2})^{2}, e_{0}^{=0}.$$
(34)

Application of the algorithm of section five gives the unique ML estimators of  $\beta$ ,  $\rho$  and  $\sigma^2$ .

The information matrix reduces to

$$\Psi = \begin{bmatrix} \frac{1}{\sigma^2} X'A'AX & 0 & 0\\ 0 & \frac{1}{1-\rho^2} (n - \frac{1-\rho^2 n}{1-\rho^2}) & 0\\ 0 & 0 & \frac{n}{2\sigma^4} \end{bmatrix} .$$
 (35)

#### Case (ii)

Kadiyala (1968) suggested  $\phi = \sqrt{1-\rho^2}$ , which thereafter appeared in the textbooks (e.g. Theil (1971), p.253).

The condition for  $\boldsymbol{\rho}$  is then

$$\rho \sum_{i=1}^{n-1} e_{i}^{2} = \sum_{i=1}^{n-1} e_{i+1} - \frac{\rho}{1-\rho^{2}} \sigma^{2} .$$
(36)

Define 
$$a = \sigma^{-2} \frac{\Gamma^{-1}}{\Sigma} e_{i}^{2}$$
,  $c = \sigma^{-2} \frac{\Gamma^{-1}}{\Sigma} e_{i+1}$ , and  $f(\rho) = a\rho + \frac{\rho}{1-\rho^{2}}$ ,

then (36) reduces to  $f(\rho) = c$ .

On the interval (-1,1)  $f(\rho)$  is a monotonically increasing function of  $\rho$ . Moreover  $\lim_{\rho \uparrow 1} f(\rho) = \infty$  and  $\lim_{\rho \uparrow -1} f(\rho) = -\infty$ .

Thus for every c there is one unique solution of  $f(\rho) = c$  in the interval (-1,1). The algorithm of section five thus leads to the unique ML estimators of  $\beta$ ,  $\rho$  and  $\sigma^2$ . The information matrix is

$$\Psi = \begin{bmatrix} \frac{1}{\sigma^2} X'A'AX & 0 & 0 \\ 0 & \frac{1}{1-\rho^2} (n-1+\frac{2\rho^2}{1-\rho^2}) & \frac{-\rho}{\sigma^2 (1-\rho^2)} \\ 0 & \frac{-\rho}{\sigma^2 (1-\rho^2)} & \frac{n}{2\sigma^4} \end{bmatrix} .$$
 (37)

Of course, asymptotically the two cases are equivalent.

#### 9. Zellner-type regressions

The formulae (25) and (26) are readily applied to the following two well-known cases:

#### Case (i): iterated Zellner

In Zellner's (1962) case of seemingly unrelated regressions we have 12)

$$\Omega = \Sigma \otimes I.$$
 (38)

We therefore put  $\Gamma = I$  and Q = I in (25) and find

$$\widehat{\Sigma} = \frac{1}{T} E'E, \tag{39}$$

where

$$E = [e_1, e_2, ..., e_p].$$

This shows again <sup>13)</sup> that continuing Zellner's estimation procedure until convergence yields the ML estimator.

The information matrix is

$$\Psi = \begin{bmatrix} X'\Omega^{-1}X & 0 \\ 0 & \frac{1}{2}\Psi_{\sigma\sigma} \end{bmatrix} , \qquad (40)$$

where  $\Psi_{gg}$  is defined in (26.vi).

#### Case (ii): iterated Parks

Parks (1967) investigated a system of regression equations where the disturbances are both serially and contemporaneously correlated, and he proposed a three-step estimator for  $\beta$ , which he proved to be consistent and asymptotically efficient. The covariance matrix in this case <sup>14</sup>) is

$$\Omega = Q(\Sigma \otimes I)Q', \qquad (41)$$

In some applications we have  $\Omega = I \otimes \Sigma$  or  $\Omega = \Gamma \otimes \Sigma$ . The formulae for these cases may be derived in a similar fashion.

<sup>13)</sup> See Dhrymes (1971).

Our model differs slightly from Parks', viz. in the specification of the initial value of the disturbances. See the discussion in the previous section.

where 
$$Q = \begin{bmatrix} Q_1 & 0 \\ & \ddots & \\ 0 & & Q_p \end{bmatrix}$$
 and  $Q_i^{-1} = \begin{bmatrix} 1 & & \\ -\rho_i & \ddots & \\ & \ddots & \\ & & -\rho_i & 1 \end{bmatrix}$  (i=1...p).

Clearly, |Q| does not depend upon the  $\rho_{\mathbf{i}}$ , which implies that

$$\operatorname{tr} \frac{\partial Q^{-1}}{\partial \rho_i} Q = 0$$
 (i=1...p).

Further, 
$$\frac{\partial Q_{i}^{-1}}{\partial \rho_{j}} = \begin{bmatrix} A, & \text{if } i=j \\ 0, & \text{if } i\neq j \end{bmatrix}$$

where 
$$A = \begin{bmatrix} 0 \\ -1 \\ & \ddots \\ & & -1 \end{bmatrix}$$
 (42)

It then follows from (25) that the  $\theta$ -conditions are

(i) 
$$\operatorname{tr} Z\Sigma^{-1}Z_{i}^{!} = 0$$
 (i=1...p)  
(ii)  $\Sigma = \frac{1}{T} Z^{!}Z$  (43)

where  $Z = [Q_1^{-1}e_1, \dots, Q_p^{-1}e_p]$ , and

$$\tilde{Z}_{i} = [0 \dots 0, Ae_{i}, 0 \dots 0]$$
 (i=1...p).

Let  $\sigma^{ij}$  be the typical element of  $\Sigma^{-1}$ , then the condition (43.i) reduces to

$$\sum_{j=1}^{p} \sigma^{ij} e_{i}^{!} A' Q_{j}^{-1} e_{j}^{!} = 0 \qquad (i=1...p) .$$
(44)

Now 
$$A'Q_{j}^{-1} = \begin{bmatrix} \rho_{j} & -1 & & \\ & \ddots & & \\ & & \ddots & \\ & & \rho_{j} & -1 \\ & & & 0 \end{bmatrix} = \rho_{j}R_{1} - R_{2}$$
,

where 
$$R_1 = \begin{bmatrix} 1 & & & 0 \\ & \ddots & & \\ & & 1 \\ 0 & & & 0 \end{bmatrix}$$
 and  $R_2 = \begin{bmatrix} 0 & 1 & & \\ & \ddots & \ddots & \\ & & \ddots & 1 \\ & & & 0 \end{bmatrix}$ .

Then 
$$e_{i}^{A'Q_{j}^{-1}e_{j}} = \rho_{j}e_{i}^{R}e_{j} - e_{i}^{R}e_{j}$$
,

so that (44) can be written as

$$\sum_{j=1}^{p} (\sigma^{ij} e_i^! R_1 e_j) \rho_j = \sum_{j=1}^{p} \sigma^{ij} e_i^! R_2 e_j \qquad (i=1...p),$$

or in matrix notation

$$(\Sigma^{-1} \circ E'R_1^E)\rho = (\Sigma^{-1} \circ E'R_2^E)s$$
,

where  $\rho' = (\rho_1 \dots \rho_p)$ , s is a vector consisting of p 1's and  $C = [c_{ij}d_{ij}]$  is the Schur product.

The  $\theta$ -conditions (43) may now be written as

$$\begin{bmatrix}
(i) & \hat{\rho} = (\hat{\Sigma}^{-1} \circ E'R_1E)^{-1}(\hat{\Sigma}^{-1} \circ E'R_2E)s \\
(ii) & \hat{\Sigma} = \frac{1}{T} \hat{Z}'\hat{Z}.
\end{bmatrix} (45)$$

We have to make sure that the expressions in (45) exist, i.e. that  $\widehat{\Sigma}$  and  $\widehat{\Sigma}^{-1}$  • E'R<sub>1</sub>E have rank p. Since the Schur product of two positive definite matrices is also positive definite (see Bellman (1970, p.95)), sufficient for  $\widehat{\Sigma}^{-1}$  • E'R<sub>1</sub>E to be positive definite is that  $\widehat{\Sigma}$  is positive definite and E'R<sub>1</sub>E is nonsingular. Let E be the (T-1,p) matrix that is derived from E by deleting its last row, then sufficient for  $\widehat{\Sigma}$  and  $\widehat{\Sigma}^{-1}$  • E'R<sub>1</sub>E to be positive definite is that

rank (Z)= rank (
$$\tilde{E}$$
) = p .

When we now add the condition for  $\beta$  to the  $\theta$ -conditions (45), it is clear that we have formed three well-defined functions:

$$\begin{cases} (i) & \hat{\beta} = \beta(\hat{\rho}, \hat{\Sigma}) = [X'(\hat{Q}^{-1})'(\hat{\Sigma}^{-1} \otimes I)\hat{Q}^{-1}X]^{-1}X'(\hat{Q}^{-1})'(\hat{\Sigma}^{-1} \otimes I)\hat{Q}^{-1}y \\ (ii) & \hat{\rho} = \rho(\hat{\beta}, \hat{\Sigma}) = (\hat{\Sigma}^{-1} \cdot E'R_1E)^{-1}(\hat{\Sigma}^{-1} \cdot E'R_2E)s \end{cases}$$

$$(46)$$

$$(iii) & \hat{\Sigma} = \Sigma(\hat{\rho}, \hat{\beta}) = \frac{1}{T} \hat{Z}'\hat{Z}.$$

One iterative scheme to find the solution of (46) would be as follows:

(i) Choose the initial values  $\rho^{(0)}$  and  $\Sigma^{(0)}$ 

(ii) 
$$\hat{\beta}^{(0)} = \beta(\rho^{(0)}, \Sigma^{(0)})$$
 and  $e^{(0)} = y - x\hat{\beta}^{(0)}$ 

(iii) 
$$\hat{\rho}^{(1)} = \rho(\hat{\beta}^{(0)}, \Sigma^{(0)})$$

(iv) 
$$\hat{\beta}^{(1)} = \beta(\hat{\rho}^{(1)}, \hat{\Sigma}^{(0)})$$
 and  $e^{(1)} = y - X\hat{\beta}^{(1)}$ 

(v) 
$$\hat{\Sigma}^{(1)} = \Sigma(\hat{\rho}^{(1)}, \hat{\beta}^{(1)})$$

(vi) 
$$\hat{\beta}^{(2)} = \beta(\hat{\rho}^{(1)}, \hat{\Sigma}^{(1)})$$
 and  $e^{(2)} = y - x\hat{\beta}^{(2)}$ 

etcetera until convergence.

Another scheme, equally feasible, would be to choose  $\rho^{(0)}$  and  $\Sigma^{(0)}$  and then calculate  $\hat{\beta}^{(0)}$ ,  $\hat{\rho}^{(1)}$ ,  $\hat{\Sigma}^{(1)}$ ,  $\hat{\beta}^{(1)}$ ,  $\hat{\rho}^{(2)}$ ,  $\hat{\Sigma}^{(2)}$ ,  $\hat{\beta}^{(2)}$ , etcetera. There are several other possibilities.

Parks' procedure can be completely described in terms of the first scheme, based on the initial values  $\rho^{(0)}=0$  and  $\Sigma^{(0)}=I$ . In that case

$$\hat{\beta}^{(0)} = (X'X)^{-1}X'y \quad \text{and} \quad e^{(0)} = y - X\hat{\beta}^{(0)}$$

$$\hat{\rho}_{j}^{(1)} = \begin{pmatrix} T-1 \\ \sum e_{jk} e_{j,k+1} \\ k=1 \end{pmatrix} / \sum_{k=1}^{T-1} e_{jk}^{2} \qquad (j=1...p) \quad \text{and} \quad \hat{Q} = Q(\hat{\rho}^{(1)})$$

$$\hat{\beta}^{(1)} = \left[ X'(\hat{Q}^{-1})'\hat{Q}^{-1}X \right]^{-1}X'(\hat{Q}^{-1})'\hat{Q}^{-1}y ; e^{(1)} = y - X\hat{\beta}^{(1)}; \hat{Z} = Z(\hat{Q}, e^{(1)})$$

$$\hat{\Sigma}^{(1)} = \frac{1}{T} \hat{Z}'\hat{Z}$$

$$\hat{\beta}^{(2)} = [X'(\hat{Q}^{-1})'(\hat{\Sigma}^{(1)})^{-1} \otimes I)\hat{Q}^{-1}X^{-1}X'(\hat{Q}^{-1})'(\hat{\Sigma}^{(1)})^{-1} \otimes I)\hat{Q}^{-1}Y.$$

 $\hat{\beta}^{(2)}$  is Parks' so-called 'three-step' estimator. However, continuing the procedure until convergence yields the ML estimator.

To construct the information matrix we proceed as follows:

$$K_{i} = \frac{\partial Q^{-1}}{\partial \rho_{i}} Q = Y^{ii} \otimes AQ_{i}$$
 (i=1...p),

where  $Y^{ii}$  is defined in (24) and A in (42).

$$K_{i}K_{j} = \begin{bmatrix} 0 & \text{if } i\neq j \\ \\ Y^{ii} \otimes (AQ_{i})^{2} & \text{if } i=j . \end{bmatrix}$$

$$AQ_{\mathbf{i}} = \begin{bmatrix} 0 & & & & \\ -1 & \ddots & & & \\ & \ddots & \ddots & \\ & & -1 & 0 \end{bmatrix} \begin{bmatrix} 1 & & & & \\ \rho_{\mathbf{i}} & \ddots & & & \\ \vdots & \ddots & \ddots & \ddots & \\ \rho_{\mathbf{n-1}} & \ddots & \vdots & \rho_{\mathbf{i}} & 1 \end{bmatrix} = - \begin{bmatrix} 0 & & & & 0 \\ 1 & \ddots & & & \\ \rho_{\mathbf{i}} & \ddots & \ddots & \ddots & \\ \vdots & \ddots & \ddots & \ddots & \vdots & \vdots \\ \rho_{\mathbf{n-2}} & \dots & \rho_{\mathbf{i}} & 1 \end{bmatrix}.$$

It is clear that

and 
$$tr(AQ_{i}) = tr(AQ_{i})^{2} = trK_{i}K_{j} = 0$$

$$tr(AQ_{i})^{\dagger}AQ_{j} = \sum_{k=0}^{n-2} \sum_{h=0}^{k} (\rho_{i}\rho_{j})^{h}.$$

Now let  $\lambda = \rho_i \rho_j$ , then

$$\sum_{k=0}^{n-2}\sum_{h=0}^{k}\lambda^{h}=\sum_{k=0}^{n-2}\frac{1-\lambda^{k+1}}{1-\lambda}=\frac{1}{1-\lambda}\left[n-1-\frac{\lambda(1-\lambda^{n-1})}{1-\lambda}\right]$$

$$= \frac{n}{1-\lambda} - \frac{1-\lambda^n}{(1-\lambda)^2} .$$

From this it follows that

$$trK_{\mathbf{i}}^{!}(\Sigma^{-1} \otimes I)K_{\mathbf{j}}(\Sigma \otimes I)$$

$$= tr(Y^{\mathbf{i}\mathbf{i}} \otimes Q_{\mathbf{i}}^{!}A')(\Sigma^{-1} \otimes I)(Y^{\mathbf{i}\mathbf{i}} \otimes AQ_{\mathbf{j}})(\Sigma \otimes I)$$

$$= tr(Y^{\mathbf{i}\mathbf{i}}\Sigma^{-1}Y^{\mathbf{j}\mathbf{j}}\Sigma) \otimes (Q_{\mathbf{i}}^{!}A'AQ_{\mathbf{j}})$$

$$= \operatorname{tr}(Y^{ii} \Sigma^{-1} Y^{jj} \Sigma) \otimes (Q_{i}^{!} A^{!} A Q_{j}^{!})$$

$$= \sigma^{ij} \sigma_{ij} \left[ \frac{n}{1 - \rho_{i} \rho_{j}} - \frac{1 - (\rho_{i} \rho_{j}^{!})^{n}}{(1 - \rho_{i} \rho_{j}^{!})^{2}} \right].$$

Further

$$\begin{split} \operatorname{tr} \mathsf{K}_{\mathbf{i}}^{!}(\boldsymbol{\Sigma}^{-1} \boldsymbol{Y}^{\mathrm{hk}} \otimes \boldsymbol{I}) &= \operatorname{tr}(\boldsymbol{Y}^{\mathbf{ii}} \otimes \boldsymbol{Q}_{\mathbf{i}}^{!} \boldsymbol{A}^{!})(\boldsymbol{\Sigma}^{-1} \boldsymbol{Y}^{\mathrm{hk}} \otimes \boldsymbol{I}) \\ &= \operatorname{tr}(\boldsymbol{Y}^{\mathbf{ii}} \boldsymbol{\Sigma}^{-1} \boldsymbol{Y}^{\mathrm{hk}}) \ \operatorname{tr}(\boldsymbol{Q}_{\mathbf{i}}^{!} \boldsymbol{A}^{!}) = 0 \ . \end{split}$$

Using the formulae in (26) we have

$$\Psi_{\theta} = \begin{bmatrix} \Psi_{\rho\rho} & 0 \\ 0 & \Psi_{\sigma\sigma} \end{bmatrix} , \qquad (47)$$

where 
$$(\Psi_{\rho\rho})_{ij} = 2\sigma^{ij}\sigma_{ij} \left[ \frac{n}{1-\rho_{i}\rho_{j}} - \frac{1-(\rho_{i}\rho_{j})^{n}}{(1-\rho_{i}\rho_{j})^{2}} \right]$$
 (i,j=1...p),

and  $\Psi_{\sigma\sigma}$  is defined in (26.vi).

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